Stationary Solutions to the Vlasov–Poisson System in Singular Geometries

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<u>Outline</u>

The model

Existence and uniqueness

General properties

Corner behaviour

Behaviour w.r.t. mass (Maxwellian case)

Numerical simulation

Open problems

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The Name of the Game:

Plasma near a conducting sharp end



Stationary Vlasov–Poisson system in $\Omega \subset \mathbb{R}^d$:

$$v \cdot \nabla_x f + E(x) \cdot \nabla_v f = 0,$$
 $(x, v) \in \Omega \times \mathbb{R}^d,$ (1)

$$E(x) = -\nabla_x \left(\phi[f] - \phi_e\right) \tag{2}$$

$$-\Delta\phi[f] = \int_{\mathbb{R}^d} f(x,v) \, dv := \rho[f], \qquad x \in \Omega, \quad + \text{ bdy cond'n}, \quad (3)$$

$$-\Delta\phi_e = \rho_e,$$
 $x \in \Omega, + bdy cond'n.$ (4)

- ▶ f(x, v): distribution function of charged particles (electrons)
 = density in phase space (x, v)
- $\rho[f](x)$: spatial density of particles.
- $\phi[f](x)$: self-consistent potential.
- $\phi_e(x)$: external (confining) potential.
- ▶ $\rho_e(x)$: density of "neutralising background" (ions).

Existence and Uniqueness

Any couple $(f, \phi[f])$ satisfying (Boltzmann problem)

$$\begin{cases} f(x,v) = \gamma \left(\frac{1}{2}|v|^2 + \phi[f](x) - \phi_e(x) - \beta\right) \\ -\Delta\phi[f] = \rho[f] \ (+ \text{ bdy cond'n}), \quad \int_{\Omega \times \mathbb{R}^d} f \, dx dv = M, \end{cases}$$
(5)

(γ arbitrary function, $M \ge 0$ given, ϕ_e given by (4)), is a solution to Problem (1–3).

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Proposition 1: Assume (inter alia) that γ is a positive, strictly decreasing function. There exists a unique solution $(f, \phi[f])$ to (5), for any mass M.

Proof: Consider the space:

$$L^1_M(\Omega \times \mathbb{R}^d) := \{ f \in L^1(\Omega \times \mathbb{R}^d) : \int_{\Omega \times \mathbb{R}^d} f \, dx dv = M \}.$$

The function f is the minimum on $L^1_M(\Omega \times \mathbb{R}^d)$ of the functional:

$$J[f] = \int_{\Omega \times \mathbb{R}^d} \left(\sigma(f) + \left(\frac{1}{2} |v|^2 - \phi_e\right) f \right) dx dv + \frac{1}{2} \int_{\Omega} |\nabla \phi[f]|^2 dx,$$

where $\sigma' = -\gamma^{-1}$. The Euler–Lagrange equation reads:

$$-\gamma^{-1}(f) + \frac{1}{2}|v|^2 - \phi_e(x) + \phi[f] - \beta = 0 \qquad (\sigma' = -\gamma^{-1})$$

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 $\begin{array}{ll} \beta: \mbox{ Lagrange multiplier of the constraint } \int_{\Omega \times \mathbb{R}^d} f \, dx dv = M. \\ \mbox{ Existence of the minimum: } \gamma \mbox{ strictly } \searrow \Longrightarrow \sigma \mbox{ strictly convex } \\ \Longrightarrow J \mbox{ strictly convex } + \mbox{ technical assumptions.} \end{array}$

Reinterpretation: non-linear elliptic problem

Problem (5) is equivalent to solving:

$$-\Delta\phi = \rho = G\left(\phi - \phi_e - \beta\right) \tag{6}$$

where $G(s) := C_d \int_0^{+\infty} \gamma(s+r) r^{d/2-1} dr$ and β is defined by: $\int_{\Omega} G(\phi - \phi_e - \beta) = M.$

Boundary condition:

$$\phi = 0 \text{ on } \Gamma_C \cup \Gamma_D, \quad \partial_\nu \phi = 0 \text{ on } \Gamma_N.$$
 (7)

The data ϕ_e is solution to the linear problem:

$$\begin{split} &-\Delta \phi_e = \rho_e \in L^\infty(\Omega), \quad \partial_\nu \phi_e = 0 \text{ on } \Gamma_N, \\ &\phi_e = 0 \text{ on } \Gamma_C, \quad \phi_e = \phi_{in} \text{ on } \Gamma_D, \quad \phi_{in} \in H^{1/2}(\Gamma_D) \cap L^\infty(\Gamma_D). \\ &\partial \Omega = \Gamma_C \cup \Gamma_D \cup \Gamma_N, \text{ with } \Gamma_D \text{ and } \Gamma_N \text{ possibly empty.} \end{split}$$

Proposition 2: For any fixed β , there exists a unique solution to Problem (6-7), and ϕ is the minimum of the functional:

$$F[\phi] = \int_{\Omega} \frac{1}{2} |\nabla \phi|^2 + \mathcal{G}(\phi - \phi_e - \beta) \, dx,$$

where $\mathcal{G}' = -G$, on the space V of functions defined by :

$$V = \{ w \in H^1(\Omega) : w = 0 \text{ on } \Gamma_C \cup \Gamma_D \}.$$

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Proof: γ strictly $\searrow \implies G$ strictly $\searrow \implies \mathcal{G}$ strictly convex $\implies F$ strictly convex.

V.F.:
$$\int_{\Omega} \nabla \phi \cdot \nabla \xi = \int_{\Omega} G(\phi - \phi_e - \beta) \xi, \quad \forall \xi \in V.$$

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A First Monotonicity Property

Non-linear elliptic comparison principle (Lions): Let ϕ_1 and ϕ_2 be two solutions corresponding to $\beta = \beta_1$ and β_2 .

If
$$\beta_1 \ge \beta_2$$
 then $\phi_1 \ge \phi_2$ in Ω .

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Theorem 1: Define the mapping

$$\begin{array}{rccc} \mu: & \mathbb{R} & \longrightarrow & \mathbb{R}^+ \\ & \beta & \longmapsto & M = \int_{\Omega} G(\phi - \phi_e - \beta) \, dx, \end{array}$$

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where ϕ is the solution to Problem (6–7). Then, μ is a nondecreasing, one to one and onto mapping.

Regularity of solutions

 $f\in L^1(\Omega\times \mathbb{R}^d), \ \phi[f]\in H^1(\Omega), \ \rho[f]\in L^1(\Omega)\cap H^{-1}(\Omega).$

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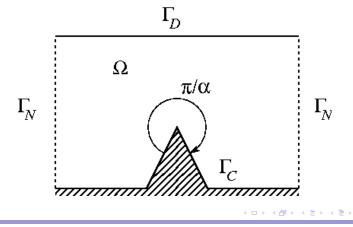
Thus, for all $p \in [1, \infty]$,

 $\phi \in \Phi_p := \{ u \in W^{1,p}(\Omega) : \Delta u \in L^p(\Omega), \ u = 0 \text{ on } \Gamma_C \cup \Gamma_D \}.$

 $p \text{ large enough: } \Phi_p \subset C(\overline{\Omega}) \implies \rho \in C(\overline{\Omega}) \text{ if } \phi_e \in C(\overline{\Omega}).$

Corner behaviour

We assume that Ω is a bounded polygonal domain in \mathbb{R}^2 , with one re-entrant corner of opening π/α $(1/2 < \alpha < 1)$.



Corner singularities

[Grisvard 85, 92...]: for all
$$p \in \left(\frac{2}{2-\alpha}, \frac{1}{1-\alpha}\right)$$
 we have:
 $\phi = \phi_R + \lambda \chi(r) r^{\alpha} \sin(\alpha \theta)$

where $\phi_R \in W^{2,p}(\Omega)$ is the regular part of ϕ , $\lambda = -\int_{\Omega} \Delta \phi P_s$ is the singularity coefficient and P_s is the dual singularity given by:

$$\begin{split} -\Delta P_s &= 0 \quad \text{in } \Omega, \quad P_s = 0 \quad \text{on } \Gamma_D \cup \Gamma_C, \quad \frac{\partial P_s}{\partial \nu} = 0 \quad \text{on } \Gamma_N; \\ P_s &= \frac{1}{\pi} r^{-\alpha} \, \sin(\alpha \theta) + \text{l.s.t.} \quad \text{near the reentrant corner.} \end{split}$$

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<u>Theorem 2</u>: Let ϕ be the solution to Problem (6) and $\phi_R \in W^{2,p}(\Omega)$ the regular part. There exists $g \in L^{\infty}(\Omega)$ such that

 $\chi(r) \phi_R(r, \theta) = r \sin(\alpha \theta) g(r, \theta), \quad \|g\|_{L^{\infty}(\Omega)} \le C \|\phi_R\|_{W^{2,p}(\Omega)}.$

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Consequences:

- The singular term is **dominant** near the corner.
- Let (f₁, φ₁) and (f₂, φ₂) be two solutions to Problem (5) associated to M₁ and M₂ respectively.

If $M_1 \ge M_2$, then $\lambda_1 \ge \lambda_2$.

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• For $\beta \geq -G^{-1}(||\rho_e||_{L^{\infty}})$, we have $\phi \geq \phi_e$ in Ω and $\lambda \geq \lambda_e$.

Behaviour w.r.t. mass

Now we assume a Maxwellian distribution: $\gamma(s) = e^{-s}$, Problem (5) becomes: (Maxwell–Boltzmann problem)

$$-\Delta\phi = \kappa e^{\phi_e - \phi} := \rho, \quad \int_{\Omega} \rho \, dx = M. \tag{8}$$

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<u>Theorem 3</u>: As $M \rightarrow 0$, we have

$$\kappa \sim M \Big(\int_{\Omega} \mathrm{e}^{\phi_e} \, dx \Big)^{-1} \quad \text{and} \quad \frac{\lambda}{\lambda} \sim \kappa \int_{\Omega} \mathrm{e}^{\phi_e} \, \underline{P_s} \, dx.$$

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Proposition 3: As $M \to \infty$, we have $\kappa \to \infty$ and

$$\begin{split} \phi &\to \infty \quad \text{a.e. in } \Omega, \quad \rho/\kappa \to 0 \quad \text{in } L^p(\Omega), \quad \forall p < \infty, \\ \phi/\kappa &\to 0 \quad \text{in } H^1(\Omega) \cap C(\overline{\Omega}). \end{split}$$

<u>Remark:</u> a boundary layer appears near Dirichlet boundaries.

Numerical simulation

$$\mathsf{Pbm} (8) \iff \begin{array}{l} \mathsf{minimise} \quad \mathcal{J}[\rho] = \int_{\Omega} (\rho \ln \rho - \phi_e \, \rho + \frac{1}{2} |\nabla \phi[\rho]|^2) \, dx \\ \mathsf{on} \qquad L^1_M(\Omega) = \big\{ \rho \in L^1(\Omega) : \int_{\Omega} \rho = M \big\}. \end{array}$$

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Numerical simulation

Pbm (8)
$$\iff$$
 minimise $\mathcal{J}[\rho] = \int_{\Omega} (\rho \ln \rho - \phi_e \rho + \frac{1}{2} |\nabla \phi[\rho]|^2) dx$
on $L^1_M(\Omega) = \{\rho \in L^1(\Omega) : \int_{\Omega} \rho = M\}.$

Algorithm:

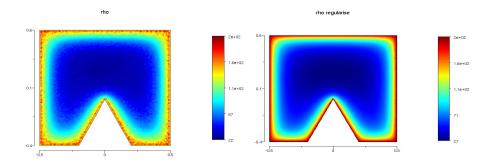
- Initialization: choose $\rho^0 \in L^1_M(\Omega)$ and $\ell \in \mathbb{N}$.
- Step n+1: set $\rho^{n,0} := \rho^n$, then
 - For $j = 1, ..., \ell$ compute $\rho^{n,j} = \text{result of one conjugate gradient iteration}$ for \mathcal{J} on $L^1_M(\Omega)$, starting from $\rho^{n,j-1}$.

• Regularization: solve
$$-\Delta \phi^{n+1} = \rho^{n,\ell}$$
, then $\rho^{n+1} = M e^{\phi_e - \phi^{n+1}} / (\int_{\Omega} e^{\phi_e - \phi^{n+1}}).$

Stop: $\|\rho^{n+1} - \rho^{n,\ell}\| < \epsilon M.$

<u>Remark:</u> solution of Laplacian by singular complement.

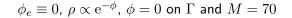
$$\phi_e \equiv 0$$
, $\rho \propto e^{-\phi}$, $\phi = 0$ on Γ and $M = 70$

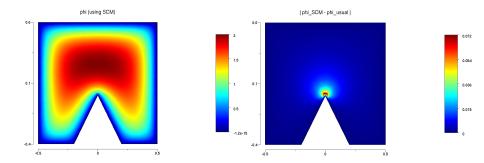


Without regularization, ρ is very noisy ($L^1(\Omega)$ hardly regular).

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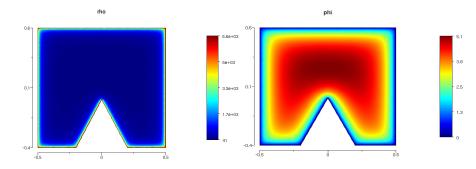




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SCM does not dramatically improve computation of ϕ : non-linear effects stronger than singular behaviour?

$$\phi_e \equiv 0$$
, $\phi = 0$ on Γ and $M = 500$

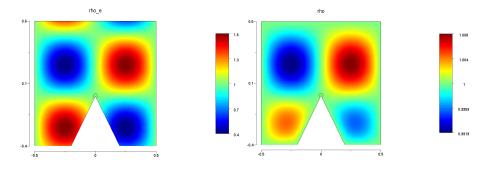


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The corner singularity is "hidden" in the boundary layer.

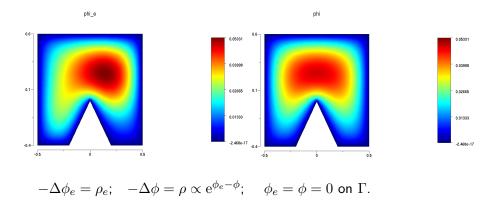
An example with a neutralising background



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 $\rho_e = 1 + \epsilon \sin(2\pi x) \sin(2\pi y); \quad \rho$ has the same mass as ρ_e .

An example with a neutralising background



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- Extension to time-dependent problems:
 - Quasi-neutral models: fluid (kinetic) ions + "Boltzmannian" electrons
 - Full Vlasov–Poisson... Vlasov–Maxwell...
 Mere existence of solutions unknown.
- Realistic modelling of lightning???