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Non-autonomous integrals (1)

Problem: regularity results for local minimizers of functionals

$$J[w] := \int_{\Omega} F(\cdot, \nabla w) \, dx \tag{0.1}$$

with a function $F: \Omega \times \mathbb{R}^{nN} \to [0, \infty)$ and a domain $\Omega \subset \mathbb{R}^n$.

Anisotropic growth conditions: for all Z, Q ∈ ℝ^{nN} and all x ∈ Ω we have

$$C_1 |Z|^p - c_1 \le F(x, Z) \le C_2 |Z|^q + c_2$$

with constantes C_1 , $C_2 > 0$, c_1 , $c_2 \ge 0$.

 If p = q there is no problem to extend the regularity statements from the autonomous case to the situation with x-dependence.

Non-autonomous integrals (2)

- Before Esposito, Leonetti und Mingione found rather surprising counterexamples (see [ELM]) most authors ignored x-dependence for a technical simplification of their proofs.
- ▶ We assume (*p*, *q*)-ellipticity:

$$\lambda (1+|Z|^2)^{\frac{p-2}{2}} |Q|^2 \le D_P^2 F(x,Z)(Q,Q) \le \Lambda (1+|Z|^2)^{\frac{q-2}{2}} |Q|^2$$
(A1)

for all $Z, Q \in \mathbb{R}^{nN}$ and all $x \in \Omega$ with positive constants λ, Λ and exponents 1 .

• We suppose for all $Z \in \mathbb{R}^{nN}$ and all $x \in \Omega$

$$|\partial_{\gamma} D_{P} F(x, Z)| \le \Lambda_{2} (1 + |Z|^{2})^{\frac{q-1}{2}}$$
 (0.2)

with $\Lambda_2 > 0$ and $\gamma \in \{1, ..., n\}$.

Gap between both cases (1)

 In [ELM] Esposito, Leonetti and Mingione examine the Lavrentiev gap functional, which is defined as

$$\mathcal{L} := \inf_{u_0 + W_0^{1,q}(B,\mathbb{R}^N)} J - \inf_{u_0 + W_0^{1,p}(B,\mathbb{R}^N)} J$$

on a ball $B \Subset \Omega$ with boundary data $u_0 \in W^{1,p}(B, \mathbb{R}^N)$.

 The results of the studies from [ELM] provide the sharpness of the bound

$$q$$

for higher integrability of solutions (assuming that $D_PF(x, Z)$ is α -Hölder continuous with respect to x)

 Without this condition they have examples for Lavrentiev-phenomenon.

Gap between both cases (2)

Under the condition

$$q$$

Bildhauer and Fuchs [BF1] prove full $C^{1,\alpha}$ -regularity for N = 1 or n = 2 and partial regularity in the general vector case.

- ► This statement is in accordance with the results of [ELM].
- Under several structure conditions Bildhauer and Fuchs can improve the last result to full regularity (see [BF1]).
- Without x-dependence we know from [BF2] that the better bound

$$q$$

is sufficient for regularity.

Two problems

- If one have a look at the proof in [BF1], one see two main differences to the case of autonomous.
- ► The first obstacle is that the standard-regularization u_{δ} does not converge against the minimum u without (0.3). Thereby u_{δ} is defined as the unique minimizer of

$$\int_{B} \left[F(\cdot, \nabla w) + \delta \left(1 + |\nabla w|^2 \right)^{\frac{\widetilde{q}}{2}} \right] dx$$

in $(u)_{\epsilon} + W_0^{1,\widetilde{q}}(B,\mathbb{R}^N)$ with $\widetilde{q} > q$ and $B \Subset \Omega$.

The second obstacle in the proof in [BF1] is estimating the term

$$\int \eta^2 \partial_\gamma D_{\mathsf{P}} \mathsf{F}(\cdot, \nabla u) : \partial_\gamma \nabla u \, dx.$$

Solving the first one (1)

► To solve the first problem we work with a regularization from below: we need a function F_M such that

$$F_M(x,Z) = F(x,Z) \text{ if } |Z| \le M$$

$$F_M(x,Z) \le F(x,Z).$$

- Such a regularization from below is based on a construction from [CGM].
- We have to extend all growth conditions assumed for F uniformly in M to F_M and show isotropic growth (i.e. F_M is p-elliptic).
- A necessary assumption for the construction of F_M is

$$F(x, P) = g(x, |P|).$$
 (A3)

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Solving the first one (2)

• We define the regularization u_M as the unique minimizer of

$$J_M[w] = \int_B F_M(\cdot, \nabla w) \, dx$$

in $u + W_0^{1,p}(B, \mathbb{R}^N)$ with a ball $B \subseteq \Omega$.

This is the minimizer of an isotropic problem and so we have several regularity properties of u_M.

Solving the second one (1)

▶ To handle to critical integral we suppose for all $P, Z \in \mathbb{R}^{nN}$

$$egin{aligned} & \left| \partial_{\gamma} D_P^2 F(x,Z)(P,Z)
ight| \leq \Lambda_3 \left| D_P^2 F(x,Z)(P,Z)
ight| (1+|Z|^2)^{rac{\epsilon}{2}} \ & + \Lambda_3 (1+|Z|^2)^{rac{p+q-2}{4}} \left| P
ight| \end{aligned}$$

for $0 \leq \epsilon \ll 1$.

On account of (A3) this means

$$|\partial_{\gamma}g''(x,t)| \leq \Lambda_4 \left[g''(x,t)(1+t^2)^{rac{\epsilon}{2}} + (1+t^2)^{rac{p+q}{4}-1}
ight] \quad (A4)$$

• Example : for $f:\Omega \to (1,\infty)$ consider

$$\int_{\Omega} \left(1+|\nabla w|^2\right)^{\frac{f(x)}{2}} dx.$$

Solving the second one (2)

• To extend our growth conditions to F_M we have to suppose

$$|\partial_{\gamma}^2 g''(x,t)| \le \Lambda_5 (1+t^2)^{\frac{q-2}{2}}$$
 (A5)

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as a last assumption.

This is in accordance with

$$g''(x,t) \leq \Lambda_5(1+t^2)^{\frac{q-2}{2}}.$$

Theorems (1)

If we assume (A1)-(A5) we have the following result for local minimizers of (0.1):

- Full regularity if n = 2,
- full regularity if N = 1,
- partial regularity in general vector case.

Theorems (2)

To achieve full regularity in the general vector case we need further assumptions:

► Suppose for all
$$P, Q \in \mathbb{R}^{nN}$$
, all $x \in \overline{\Omega}$ with $\alpha \in (0, 1)$
 $\left| D^2 F(x, P) - D^2 F(x, Q) \right| \le c (1 + |P|^2 + |Q|^2)^{\frac{q-2-\alpha}{2}} |P - Q|^{\alpha}.$ (A6)

This condition is also needed in the isotropic situation.

• One of the following two conditions (only for $n \ge 5$)

(i)
$$q (A7)
(ii) $g'(x,t) \le cg''(x,t)(1+t^2)^{\frac{\omega}{2}}$ (A8)
for $\omega < \left(\frac{pn}{n-2} - q\right) + 1.$$$

Locally bounded minimizers (1)

 If we assume u ∈ L[∞]_{loc}(Ω, ℝ^N) we have dimensionless conditions between p and q: In the autonomous situation from [BF2]

$$q$$

whereas the non-autonomous situation requires the much more restrictive bound (see [BF1])

$$q .$$

How to close this gap?

Locally bounded minimizers (2)

 We get full regularity if we suppose (A1), (A3)-(A6), (A9) and

$$g'(x,t) \le cg''(x,t)(1+t^2)^{\frac{\omega}{2}}$$

for $\omega < (p+2-q)+1.$ (A10)

- ▶ It is not possible to extend (A10) to g_M (note $F_M(x, Z) = g_M(x, |Z|)$) uniformly in M.
- Therefore we use the *M*-regularization to show ∇u ∈ L^{p+2}_{loc}(Ω, ℝ^{nN}) which is possible without (A10).
- Then we have a W^{1,q}_{loc}-minimizer and thereby the δ-regularization converge.
- Use this to show local boundedness of ∇u .

Overview

known results	new results
q	q
	$F(x,Z) = g(x, Z), D_x g'' \leq$
• FR for $n = 2$, $N = 1$	• FR for $n = 2$, $N = 1$
or GV with SC	or GV with SC
• PR in GV [BF1], 2005	• PR in GV
$q < p+1, u \in L^\infty_{loc}(\Omega, \mathbb{R}^N)$	$q < p+2, \ u \in L^\infty_{loc}(\Omega, \mathbb{R}^N)$
	$F(x,Z) = g(x, Z)$, $D_xg'' \leq$
	$g'(x,t)\leq c(1+t^2)^{rac{\omega}{2}}g''(x,t)$
• FR for $N = 1$ or GV with SC	• FR for $N = 1$ or GV with SC
[BF1], 2005	

Nonlinear Stokes problem (1)

Minimizing functionals of the form

$$\widetilde{J}[v] := \int_{\Omega} \{H(\epsilon(v)) - f \cdot v\} dx, \quad \epsilon(v) = \frac{1}{2}(\nabla v + \nabla v^{T})$$

subject to the constraint div(v) = 0.

- Applications: mathematical fluid mechanics.
- Minimizers correspond to the following system of partial differential equations

$$\begin{cases} \operatorname{div} \{\nabla H(\epsilon(v))\} = \nabla \pi - f \quad \text{on } \Omega, \\ \operatorname{div} v = 0 \qquad \text{on } \Omega, \end{cases}$$
(0.2)

- The solution v : Ω → ℝⁿ is the velocity field and π : Ω → ℝ is the pressure.
- Here Ω denotes a domain in ℝⁿ (n ∈ {2,3}), f : Ω → ℝⁿ is a system of volume forces.

Nonlinear Stokes problem (2)

Examples for the density H

- Classical Stokes problem: $H(\epsilon) = |\epsilon|^2$
- Power law fluids: $H(\epsilon) = (1 + |\epsilon|^2)^{\frac{p}{2}}$, 1
- ▶ Non-Newtanion fluids: H has anisotropic behaviour in ϵ
- Especialy Electrorheological fluids: $H(\epsilon) = (1 + |\epsilon|^2)^{\frac{p(x)}{2}}$

Assume that H satisfies the conditions (A1)-(A5) and consider minimizers of

$$\widetilde{J}[w] := \int_{\Omega} \{H(\cdot, \epsilon(w)) - f \cdot w\} dx, \quad \operatorname{div}(w) = 0.$$

The results about full regularity for n = 2 and partial regularity in the general vector case extend to this situation.

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