PDEs and Variational Problems with random coefficients

Nicolas Dirr

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Introduction

- Setting: Random integrands/PDEs with random coeff.
- Motivation: Interface evolution in random media
- Existence/Nonexistence: Nonnegative solutions for semilinear random PDE
- Uniqueness: Unique minimizer for random functional with double-well structure.
- Review of random homogenization

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General form:

$$F(D^2u, Du, u, x, \omega) = 0,$$

where the random function

$$\boldsymbol{F}:\mathbb{R}_{\text{sym}}^{\textit{nxn}}\times\mathbb{R}^{n}\times\mathbb{R}\times\Omega\rightarrow\mathbb{R}^{m}$$

(here m = 1) satisfies **deterministic bounds**/structural conditions. (E.g. continuous, uniformly elliptic etc.) Probability measure \mathbb{P} on all equations with these bounds Not considered:

Random initial conditions
 SPDEs

Usually: Law **translation invariant and ergodic**, so "almost sure" results for large-scale behaviour.

Homogenization: Behaviour of solns. for $F(D^2u, Du, u, x/\epsilon, \omega) = 0$,

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Random Functionals

Find minimizer in a suitable function space (e.g. $H^{1,2}(D)$) of

$$u(x)\mapsto \int_D F(Du,u,x,\omega)dx$$

Minimizer will be random function.

- $D = \mathbb{R}^n$: Minimizer under compact perturbations.
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Key features of Models:

Evolution decreases free energy

- Free energy is surface energy, i.e. area of interface
- Heterogeneities influence free energy locally (on small scale)

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Zoom in on scale of heterogeneities

Perturbed Area Functional/Forced MCF

Zoom in on scale of heterogeneities: Liapunov functional (formal):

Area
$$(\Sigma) + \int_{\mathbb{R}^{n+1} \cap E} f(X) dX$$
 where $\Sigma = \partial E$.



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Gradient flow:

$$V_X = \kappa_X + f(X), \ X \in \Sigma(t) \subset \mathbb{R}^{n+1}$$

 κ_X mean curvature of Σ at point X, V_X normal velocity at point X.

Behaviour on Large Scale:

("Undo zooming in")

$$V_X = \kappa_X + f(X, \omega), \ X \in \Sigma(t) \subset \mathbb{R}^{n+1}$$

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De-pinning Threshold F_c

Scaling law for effective velocity as function of F and for "oscillation" of interface.

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Motivation

Related Homogenization Problem

Interface as level set: $\Sigma(t) = \{x \in \mathbb{R}^{n+1} : w(x, t) = 0\}$

$$V = \epsilon \kappa + f\left(\frac{x}{\epsilon}\right) \Rightarrow w_t = \epsilon \operatorname{tr}\left[\left(I - \frac{1}{|\nabla w|^2} \nabla w \otimes \nabla w\right) D^2 w\right] + f\left(\frac{x}{\epsilon}\right) |\nabla u|$$
$$V = c(\nu) \Rightarrow \bar{w}_t = c\left(\frac{\nabla \bar{w}}{|\nabla \bar{w}|}\right) |\nabla \bar{w}|$$

"Singular" Homogenization: Averaging and singular limit.

- Degenerate, nonlinear
- f(x) may change sign

Forcing f(x) strictly positive (+additional conditions), not random:

P.-L. Lions, P.E. Souganidis, (2005),

Additional conditions: Caffarelli, Monneau

Connection: Level sets evolve by (forced) MCF (Chen-Giga-Goto) Random case mostly open! Look for simplified model:

Random Obstacle Model.

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Introduction

Motivation

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Forced Mean Curvature Flow/Semilinear "Approx."

Forced MCF (Gradient flow of perturbed surface energy): $V_{x,u} = \kappa_{x,u} + f(x, u) + F$ $\uparrow u$

If surface is graph (x, u(x, t)) then $u(x, t) : \mathbb{R}^n \times \mathbb{R}_+ \to \mathbb{R}$ solves

$$\partial_t u = \sqrt{1 + |\nabla u|^2} \operatorname{div}\left(\frac{\nabla u}{\sqrt{1 + |\nabla u|^2}}\right) + \sqrt{1 + |\nabla u|^2} (f(x, u) + F).$$

gradient small, then (heuristic) approximation: semilinear PDE

 $u_t = \Delta u + f(x, u) + F$, $F \ge 0$: external driving force.

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$$\begin{array}{c}
 u \\
 (x,u(x,t)) \\
 \hline
 x
\end{array}$$

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Gradient flow with Lyapunov functional:

$$\int \left(\sqrt{1+|\nabla u|^2} + \left[\int_0^{u(x)} f(x,s,\omega)ds\right] + Fu\right) dx$$

Direct Observation of Pinning and Bowing of a Single Ferroelectric Domain Wall, T. J. Yang, Venkatraman Gopalan, P. J. Swart, U. Mohideen, Physical Review Letters 82, 1999

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Random Coefficients

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The Random Obstacle Model



$$\partial_t u(x,t,\omega) = \Delta u(x,t,\omega) + f(x,u(x,t,\omega),\omega) + F$$
 on \mathbb{R}^n
 $u(x,0) = 0$

Quenched Edwards-Wilkinson Model (QEW)

Dynamic phase transitions in ferroic systems with pinned domain walls. W. Kleemann. MFO Phasenübergänge, 20.-26. 06. 2004

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Important: Comparison Principle. If u, v solns., $u(T) \le v(T)$, (+b.c.) then $u(T + s) \le v(T + s)$ for all $s \ge 0$.

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Questions: Pinning/De-pinning: Is it true that

- \bullet 0 < F < F_ $_{*}$: nonnegative stationary solution exists
- $F > F_*$: **no** nonnegative stationary solution exists?

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$$\partial_{\tau} v(y,\tau,\omega) = \epsilon \Delta v(y,\tau,\omega) + f(\epsilon^{-1}y,\epsilon^{-1}v(y,\tau,\omega),\omega) + F$$

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• 0 < *F* < *F*_{*} : nonnegative stationary solution exists • *F* > *F*_{*} : **no** nonnegative stationary solution exists? "effective velocity" on scale $\tau = \epsilon^{-1}t$, $y = \epsilon^{-1}x$. $\partial_{\tau}\bar{v}(y,\tau,\omega) = \bar{c}$

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- "effective velocity" on scale $\tau = \epsilon^{-1} t$, $y = \epsilon^{-1} x$. $\partial_{\tau} \bar{v}(y, \tau, \omega) = \bar{c}$ • Periodic: Such F_* exists, velocity $\sim \sqrt{F - F_*}$
- $F = F^*$? Periodic: Stationary solution due to compactness (D.-Yip)

What happens at F = F*?

• Periodic environment (compactness): Stationary solution exists as u.c. limit of stationary solutions for $F < F_*$.

• Random environment: Zero Velocity **AND** non-existence of stationary solution possible

 $\dot{X} = F + \sin(2\pi x)$

 $F_* = 1$ χ cut-off, $\chi = 1$ near x = 0, $\chi = 0$ on $\mathbb{R} \setminus [-1/8, 1/8]$. Z_i i.i.d., $Z_i > 0$ a.s., $\mathbb{E}Z_0 = \infty$. (square-root behavior)

Time to cross obstacle at $i:\sim Z_i$

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Random vs. Periodic: Loss of compactness and behaviour at critical forcing in zero dim.

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Time to cross obstacle at $i: \sim Z_i$

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Random Obstacle Model: Precise Setting



$$\partial_t u(x, t, \omega) = \Delta u(x, t, \omega) + f(x, u(x, t, \omega), \omega) + F$$
 on \mathbb{R}^n
 $u(x, 0) = 0$

$$\begin{split} F \geq 0, & \text{(driving force), } \phi \text{ mollifier of } \mathbf{1}_{[-\delta,\delta]^{n+1}}(x,u), \\ & f(x,u) = \sum_{(i,j) \in \mathbb{Z}^n \times (\mathbb{Z} + \frac{1}{2})} \left(\mathbb{E}(\ell_{ij}) - \ell_{i,j}(\omega) \right) \phi(x-i,u-j) \\ & (\ell_{i,j}(\omega))_{(i,j) \in \mathbb{Z}^n \times (\mathbb{Z} + \frac{1}{2})} \text{ are a family of i.i.d. exponential random variables.} \end{split}$$

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$$0 = \Delta u(x,\omega) + f(x,u(x,\omega),\omega) + F$$
 on \mathbb{R}^n , $u(x) \ge 0$ (*)

Theorem (N.D., J. Coville, S. Luckhaus)

Let n = 1 and u solve (*) Then there exist $F_0 > 0$ such that for $F > F_0$, there is almost surely no solution of (*).

Theorem (N.D., P. Dondl, M. Scheutzow)

Let n = 1, 2. There ex. $0 < F_1$ such that for $0 < F < F_1$, (*) has almost surely a solution with $\mathbb{E}[u(x, \omega)] = c < \infty$ for all $x \in \mathbb{R}^n$.

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Barrier for/limit of

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Theorem (P. Dondl, M. Scheutzow)

- Let n = 1 There ex. $0 < F_1$ and $C_1 > 0$ such that for $F > F_1$, there ex. almost surely a solution with $\mathbb{E}[u(x, t, \omega)] \ge C_1 t$ for all $x \in \mathbb{R}$.
- Uniformly for x₁, x₂ in a fixed compact:

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$$\mathbb{P}\Big\{\omega: u(x,\omega)) \geq KN - K|x|\Big\} \geq 1 - Ce^{-rac{N}{C}}$$

- Coarse-graining: Discretise → v³, using that path between obstacles determined by values on boundary of obstacles.
- Estimate discrete Laplacian against obstacle:
 - $\Delta_d(i) + F \le G\ell_{i,[\bar{v}^\delta(i)]}(\omega)$
 - Problem: Path may pass several obstacles above same integer
- Auxiliary random measure on paths:
 - $\mathbb{P}(U(\omega) \text{ compatible with } \tilde{v}^{\delta}(l)) \leq CZ \left\{ Z^{-1} e^{-C \sum_{i} (\Delta_{d}(l) + l)_{i}} \right\}$
- Conclusion: Path crosses $KN = K|x| \Rightarrow \sum_{i} (\Delta_d(i) + F) = O(N)$ • Borel-Cantelli Lemma

$$\mathbb{P}\Big\{\omega: \ u(x,\omega)) \geq \mathcal{KN} - \mathcal{K}|x|\Big\} \geq 1 - \mathcal{C}e^{-rac{N}{C}}$$

- Coarse-graining: Discretise $\rightarrow \bar{v}^{\delta}$, using that path between obstacles determined by values on boundary of obstacles.
- Estimate discrete Laplacian against obstacle: $\Delta_d(i) + F \leq C\ell_{i,[\bar{\nu}^{\delta}(i)]}(\omega)$ Problem: Path may pass several obstacles above same integer • Auxiliary random measure on paths
 - $\mathbb{P}(u(\omega) \text{ compatible with } \overline{v}^{\delta}(i)) \leq GZ \left\{ Z^{-1} e^{-C\sum_{i}(\Delta_{\delta}(i)+F)_{+}} \right\}$



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Non-Existence

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Essential probabilistic step: Lipschitz percolation, i.e. a discrete 1-Lipschitz graph $w : \mathbb{Z}^n \to \mathbb{N}$ ex. with (z, w(z)) good for all $z \in \mathbb{Z}^n$ if $\mathbb{P}(bad)$ small, (D., Dondl, Grimmett, Holroyd, Scheutzow, Electr. J. of Prob.,)

Analyst's approach: Fixed point iteration

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Proofs

Existence

Essential probabilistic step: Lipschitz percolation, i.e. a discrete 1-Lipschitz graph $w : \mathbb{Z}^n \to \mathbb{N}$ ex. with (z, w(z)) good for all $z \in \mathbb{Z}^n$ if $\mathbb{P}(bad)$ small, (D., Dondl, Grimmett, Holroyd, Scheutzow, Electr. J. of Prob.,)



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Branching process on cones: Dies out if "closed" cells rare.

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Idea: Approximate Lipschitz graph by function s.t. $\Delta u + f(x, u, \omega) + F \leq 0$. ("convex" corners at obstacles)

 Discretization: Fix threshold R, call a box open if it contains obstacle with strength > R.



- Suppose: There exists Lipschitz graph w ≥ 1 which is contained in the open set.
- From *w* construct function $v \ge 0$ with Lipschitz-constant C(F) which solves $\Delta v = -F$ outside strong obstacles.
- Inside strong obstacles: Paraboloids.

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Area
$$(\Sigma \cap \Lambda) + \int_{\Lambda \cap E} f(X) dX$$
 where $\Sigma = \partial E$.
 $F_{\epsilon}(u) = \int_{\Lambda} \left(\frac{\epsilon}{2} |\nabla u(x)|^2 + \frac{1}{\epsilon} W(u(x)) + \frac{\alpha_{\epsilon}}{\epsilon} h\left(\frac{x}{\epsilon}, \omega\right) u(x)\right) dx$

h bounded random field, short correlation length *W* double-well potential, two minimizers ± 1 .



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Replace gradient term by nonlocal term

$$E_{\Lambda}(m,m_0) = \int_{\Lambda \times \Lambda} dx dy \frac{|\mathbf{m}(\mathbf{x}) - \mathbf{m}(\mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}} + \underbrace{2 \int_{\Lambda} dx \int_{\mathbb{R}^{n+1} \setminus \Lambda} dy \frac{|\mathbf{m}(\mathbf{x}) - \mathbf{m}_0(\mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}}}_{\text{boundary cond. } \mathbf{m}_0}$$

$$d=2, s \in (\frac{1}{2}, 1)$$
 or $d=1, s \in [\frac{1}{4}, 1)$: Unique minimiser (comp. pert.)

The functional

Randomness: $(g(z, \omega))_{z \in \mathbb{Z}^d}$, *d* space dimension family of uniformly bounded i.i.d. r.v. with mean zero and variance 1 and **Lebesgue-continuous** and symmetric distribution.

$$g(x,\omega) := \sum_{z \in \mathbb{Z}^d} g(z,\omega) \mathbf{1}_{(z+[-rac{1}{2},rac{1}{2}]^d) \cap \Lambda}(x),$$

Energy:

$$\mathcal{K}(\mathbf{v},\omega,\Lambda) = \int_{\Lambda} d\mathbf{x} \int_{\Lambda} d\mathbf{y} \frac{|\mathbf{v}(\mathbf{x}) - \mathbf{v}(\mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}} + \int_{\Lambda} W(\mathbf{v}(\mathbf{x})) d\mathbf{x} - \int_{-\infty}^{\infty} g(\mathbf{x},\omega) v(\mathbf{x}) d\mathbf{x}.$$

Boundary Cost:

$$\mathcal{W}((\mathbf{v},\Lambda),(\mathbf{u},\Lambda_1)) = 2 \int_{\Lambda} \mathrm{d}x \int_{\tilde{\mathbf{v}}_1} \mathrm{d}y \frac{|\mathbf{v}(\mathbf{x}) - \mathbf{u}(\mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}}$$

$$G^{\mathbf{v}_0}(\mathbf{v},\omega,\Lambda) = \mathcal{K}(\mathbf{v},\omega,\Lambda) + \mathcal{W}((\mathbf{v},\Lambda)(\mathbf{v}_0,\Lambda^c))$$

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Minimizer under compact perturbation

 $u : \mathbb{R}^d \to \mathbb{R}$ Minimizer under compact perturbations: For any compact subdomain $U \subset$ we have

$$G^{u}(u,\omega,U)<\infty,$$
 a.s.

and

$$G^{u}(u,\omega,U) \leq G^{v}(v,\omega,U)$$
 a.s.

for any *v* which coincides with *u* in $\mathbb{R}^d \setminus U$.

 $u : \Lambda \to \mathbb{R}$ is v^0 -minimizer if it minimizes G^{v_0} among all functions which coincide with v^0 on $\mathbb{R}^d \setminus \Lambda$. These exist by standard arguments.

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Minimizers are ordered

u min. of $G^{u}(\cdot, \Lambda)$, *v* min. of $G^{v}(\cdot, \Lambda)$, then

- if u = v on $\Lambda^c \Rightarrow u \leq v$ on Λ or $v \leq u$ on Λ
- if u < v on open subset of Λ^c , then $u \leq v$ on Λ .

In general no uniqueness even on compact domains! Idea:

$$G(u \lor v, \Lambda) + G(u \land v, \Lambda) \leq G(u, \Lambda) + G(v, \Lambda).$$

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Extremal K-minimizers

On compact domain with b.c. in general no uniqueness, but there exists maximal and minimal minimizer.

Consider now constant b.c. $\pm K$ for $K \gg 1$ and let u^{\pm,K,Λ_n} be the extremal min. with b.c. $\pm K$ on $\Lambda_n := (-n, n)^d$.

Define:

$$u^{\pm K}(x,\omega) := \lim_{n \to \infty} u^{\pm,K,\Lambda_n}(x,\omega)$$

Pointwise increasing bounded sequence, converges in better function spaces, consequence:

 $u^{\pm K}(x,\omega)$ are min. under compact perturbations!

Moreover: Translation covariant i.e. $u^{\pm K}(x,\omega)$ and $u^{\pm K}(y,\omega)$ are the same in law.

Extremal ergodic states

WANTED: Extremal min. under compact pert. on \mathbb{R}^n . If they are unique, all min. are equal.

Consequence of min. property of $u^{\pm K}$ and translation covariance: uniform bounds on $||u^{\pm K}||_{\infty}$ which do not depend on *K*.

Consequence:

$$u^{\pm}(x,\omega) := \lim_{K \to \infty} u^{\pm K}(x,\omega)$$

well defined, uniformly bounded and min. under compact pert. Show: $u^+ = u^-$ a.s. Now adapt ideas of Aizenman/Wehr

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Bound on difference of optimal energies

$$ig| G^{m{v}^+}(m{v}^+,\Lambda) - G^{m{v}^-}_1(m{v}^-,\Lambda) ig| \leq C \left\{egin{array}{cc} |\Lambda|^{rac{d-1}{d}} & ext{if }m{s} \in (rac{1}{2},1) \ |\Lambda|^{rac{d-2s}{d}} & ext{if }m{s} \in (0,rac{1}{2}) \ |\Lambda|^{rac{d-1}{d}} \log |\Lambda| & ext{if }m{s} = rac{1}{2} \end{array}
ight.$$

Note: $|\Lambda_n| \sim n^d$.

Idea: Interpolate on the boundary between u^+ and u^- , estimate "cost" by estimating singular integrals.

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Central Limit Theorem: Set-up

Note: Minimal energy and minimizer depend in complicated way on all random variables $g(z, \omega)$.

 σ -algebras:

• $\mathcal{B}_{n,i} = \sigma(\{g(z), z \in \Lambda_n, z \leq i\})$ where \leq refers to lexicographic ordering in \mathbb{Z}^d .

•
$$\mathcal{B}_{\Lambda_n} = \sigma\left(\{g(z), z \in \Lambda_n\}\right)$$

•
$$\mathcal{B}(\mathbf{0}) = \sigma\left(g(\mathbf{0})\right)$$

Consider

$$\begin{aligned} F_n(\omega) &:= & \mathbb{E}\left[\left\{G(v^+(\omega), \omega, \Lambda_n) - G(v^-(\omega), \omega, \Lambda_n)\right\} | \mathcal{B}_{\Lambda_n}\right] \\ &= & \sum_{i \in \mathbb{Z}^d \cap \Lambda_n} \left(\mathbb{E}[F_n | \mathcal{B}_{n,i}] - \mathbb{E}[F_n | \mathcal{B}_{n,i-1}]\right) := \sum_{i \in \mathbb{Z}^d \cap \Lambda_n} Y_{n,i}. \end{aligned}$$

Martingale Difference: $CLT \Rightarrow F_n \sim \sqrt{|\Lambda|}N(0, D^2)$ where

$$D^2 = \mathbb{E}\left[\left(\mathbb{E}\left[F_n|\mathcal{B}(0)\right]\right)^2\right]$$

Central Limit Theorem: Result

Deterministic bound:

$$|F_n| \leq C \left\{ egin{array}{ccc} n^{d-1} & ext{if } s \in (rac{1}{2},1) \ n^{d-2s} & ext{if } s \in (0,rac{1}{2}) \ n^{d-1} \log n & ext{if } s = rac{1}{2} \end{array}
ight. .$$

Fluctuations: $n^{d/2}$ unless $D^2 = 0$.

Contradiction if $d = 2, s \in (\frac{1}{2}, 1)$ or $d = 1, s \in [\frac{1}{4}, 1)$ unless $D^2 = 0$.

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"derivative" w.r.t. randomness

$$\omega(\mathbf{0})\mapsto \int_{Q(\mathbf{0})} \mathbf{v}^+(\omega(\mathbf{0}),\omega^{(\mathbf{0})})\mathrm{d}\mathbf{x}$$

is nondecreasing.

$$rac{\partial G(m{v}^{\pm}(\omega),\omega,\Lambda)}{\partial \omega(0)} = -\int_{(-1/2,1/2)^d}m{v}^{\pm}(x,\omega)\mathrm{d}x.$$

Absolutely cont. random variables!

Heuristic: Suppose $u(\omega)$ minimises $F(u, \omega)$.

$$\frac{\partial F(u(\omega),\omega)}{\partial \omega}|_{(u(\omega),\omega)} = \frac{\partial F(u,\omega)}{\partial u}|_{(u(\omega),\omega)} + \frac{\partial F(u,\omega)}{\partial \omega}|_{(u(\omega),\omega)}$$
$$= \frac{\partial F(u,\omega)}{\partial \omega}|_{(u(\omega),\omega)}$$
$$G(u,\omega) = \dots - \int_{\Lambda} g(x,\omega)u(x)dx$$

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Central Limit Theorem: Conclusion

$$0 = D^2 = \mathbb{E}\left[\left(\mathbb{E}\left[F_n | \mathcal{B}(0)\right]\right)^2\right] = \mathbb{E}\left[f^2(\omega(0))\right]$$
) a.s.

so 0 = f(s) a.s.

$$f'(s) = \frac{\partial G(v^+(\omega), \omega, \Lambda)}{\partial \omega(0)} \Big|_{\omega(0)=s} - \frac{\partial G(v^-(\omega), \omega, \Lambda)}{\partial \omega(0)} \Big|_{\omega(0)=s}$$
$$= \int_{(-1/2, 1/2)^d} (v^+(x, \omega) - v^-(x, \omega)) dx.$$

 $f(s) = 0 \Rightarrow (\text{mon.}) f'(s) = 0 \text{ a.s.} \Rightarrow (\text{ordered}) v^+ = v^- \text{ a.s.}$

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