

# Asymptotically correct finite difference schemes for highly oscillatory ODEs

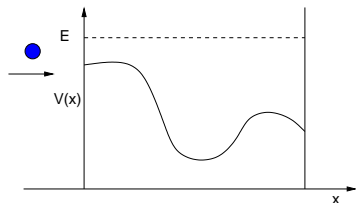
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# Application: electron injection in semiconductor (diode)



- stationary Schrödinger equation (1d):

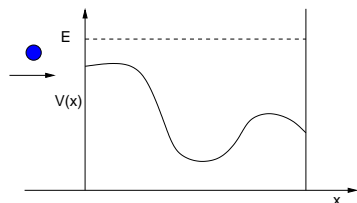
$$\underbrace{\frac{\hbar^2}{2m}}_{=\varepsilon^2} \varphi_{xx}(x) + \underbrace{(E - V(x))}_{=a(x) \geq \alpha > 0} \varphi(x) = 0, \quad x \in (0, 1)$$

- inhomogeneous open BCs:

$$\varepsilon \varphi_x(0) + i\sqrt{a(0)}\varphi(0) = 2i\sqrt{a(0)}, \quad \varepsilon \varphi_x(1) - i\sqrt{a(1)}\varphi(1) = 0$$

- reformulate as (backward) IVP for  $\psi$ :  $\varphi(x) = \frac{2i\sqrt{a(0)}}{\varepsilon\psi_x(0) + i\sqrt{a(0)}\psi(0)} \psi(x)$

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often: coupled problem for all energies  $E > 0$ ;

sharp transmission peaks w.r.t.  $E$

future: couple oscillatory to evanescent regime:  $E < V(x)$

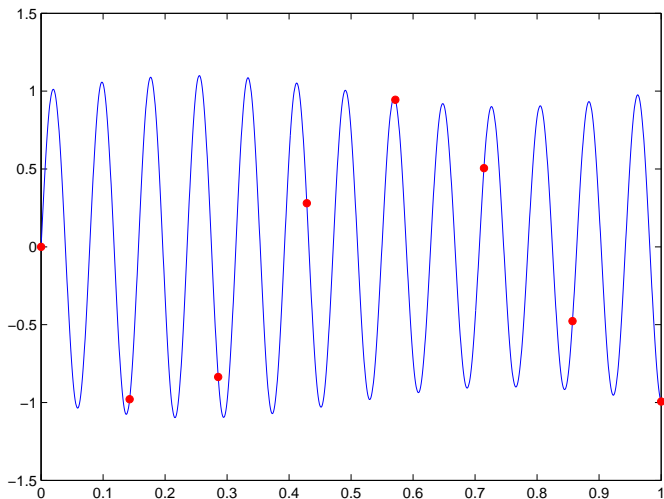
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- wavelength =  $\mathcal{O}(\varepsilon/\sqrt{a(x)})$ ;      **GOAL:** use stepsize  $h > \lambda$
- $\rightarrow$  accurate scheme that does NOT NEED to resolve the oscillations

**GOAL:** numerical scheme for  $\varepsilon^2 \varphi_{xx} + a(x)\varphi = 0$

## Outline:

- 1 analytic WKB-transformation of scalar ODE  $\rightarrow$  separate highly oscillatory term & smooth perturbation
- 2 scheme: correct uniformly in  $\varepsilon$
- 3 approximation of oscillatory integrals
- 4 error estimates
- 5 numerical example
- 6 extension to vector systems

# (1) WKB-method $\rightarrow$ for analytic preprocessing of ODE

WKB-ansatz for  $\varepsilon^2 \varphi_{xx} + a(x)\varphi = 0$ :

$$\varphi(x) \sim \exp\left(\frac{i}{\varepsilon} \sum_{p=0}^{\infty} \varepsilon^p \phi_p(x)\right), \quad \phi_p \in \mathbb{C}$$

- zeroth order:  $\varphi(x) \approx C \exp\left(\pm \frac{i}{\varepsilon} \int_0^x \sqrt{a} d\tau\right)$

- first order:

$$\varphi(x) \approx C \frac{\exp\left(\pm \frac{i}{\varepsilon} \int_0^x \sqrt{a} d\tau\right)}{\sqrt[4]{a(x)}}$$

- second order:

$$\varphi(x) \approx C \frac{\exp\left(\pm \frac{i}{\varepsilon} \int_0^x \sqrt{a(\tau)} - \varepsilon^2 \beta(\tau) d\tau\right)}{\sqrt[4]{a(x)}}, \quad \beta := -\frac{1}{2a^{1/4}} (a^{-1/4})''$$

- all: asymptotically correct for  $\varepsilon \rightarrow 0$

# WKB-FEM

[Ben Abdallah-Pinaud, 2006], [Negulescu, 2008]:

- 1<sup>st</sup> order WKB-approximation on  $(x_n, x_{n+1})$ :

$$\psi(x) = \frac{1}{\sqrt[4]{a(x)}} \left( A_n e^{i\frac{\phi_n(x)}{\varepsilon}} + B_n e^{-i\frac{\phi_n(x)}{\varepsilon}} \right)$$

$$\text{phase: } \phi_n(x) = \int_{x_n}^x \sqrt{a(\tau)} d\tau,$$

- real WKB-basis functions on cell  $(x_n, x_{n+1})$ :

$$\alpha_n(x) = -\frac{\sin \frac{\phi_{n+1}(x)}{\varepsilon}}{\sin \frac{\phi_n(x_{n+1})}{\varepsilon}} \sqrt[4]{\frac{a(x_n)}{a(x)}}, \quad \beta_n(x) = \frac{\sin \frac{\phi_n(x)}{\varepsilon}}{\sin \frac{\phi_n(x_{n+1})}{\varepsilon}} \sqrt[4]{\frac{a(x_{n+1})}{a(x)}}$$

- need “no-resonance condition” for linear independence:

$$\left| \frac{\phi_n(x_{n+1})}{\varepsilon} - k\pi \right| \geq \gamma > 0, \quad \forall k \in \mathbb{Z}$$

⇒ use finite differences instead

## 2<sup>nd</sup> order WKB transformation [AA-B.Abdallah-Negulescu]

① vector system from  $\varepsilon^2 \varphi_{xx} + a(x)\varphi = 0$ :

$$U(x) := \begin{pmatrix} \sqrt[4]{a}\varphi(x) \\ \frac{\varepsilon(\sqrt[4]{a}\varphi)'(x)}{\sqrt{a}(x)} \end{pmatrix} \rightarrow U' = \left[ \frac{1}{\varepsilon} \begin{pmatrix} 0 & \sqrt{a} \\ -\sqrt{a} & 0 \end{pmatrix} + \varepsilon \begin{pmatrix} 0 & 0 \\ 2\beta(x) & 0 \end{pmatrix} \right] U$$



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- ② diagonalize dominant part:

$$Y(x) := \frac{1}{\sqrt{2}} \begin{pmatrix} i & 1 \\ 1 & i \end{pmatrix} U \rightarrow Y' = \left[ \frac{i}{\varepsilon} \begin{pmatrix} \sqrt{a} - \varepsilon^2 \beta & 0 \\ 0 & -\sqrt{a} + \varepsilon^2 \beta \end{pmatrix} + \varepsilon \begin{pmatrix} 0 & \beta \\ \beta & 0 \end{pmatrix} \right] Y$$

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- 3 eliminate leading oscillation:

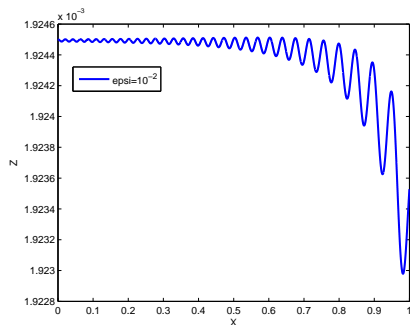
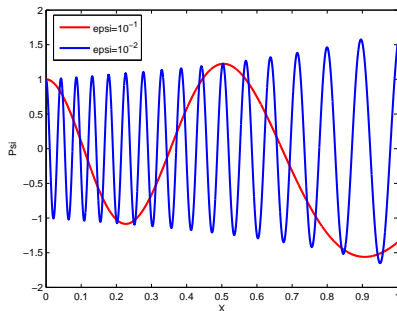
$$Z(x) := \begin{pmatrix} e^{-\frac{i}{\varepsilon}\phi(x)} & 0 \\ 0 & e^{\frac{i}{\varepsilon}\phi(x)} \end{pmatrix} Y(x) \rightarrow Z' = \underbrace{\varepsilon \begin{pmatrix} 0 & \beta e^{-\frac{2i}{\varepsilon}\phi(x)} \\ \beta e^{\frac{2i}{\varepsilon}\phi(x)} & 0 \end{pmatrix}}_{\mathcal{O}(\varepsilon)} Z$$

$$\phi(x) := \int_0^x \sqrt{a} - \varepsilon^2\beta \, d\tau \quad \dots \text{ phase of 2}^{nd} \text{ order WKB-approximation}$$

## dominant oscillations eliminated:

ex:  $\varepsilon^2 \varphi_{xx} + a(x)\varphi = 0$ ;  $a(x) = (x + \frac{1}{2})^2$ ,  $x \in (0, 1)$

- $Z$  much smoother than  $\varphi$  or  $U \rightarrow$  numerics easier



solution  $\Re \varphi(x)$  for 2 values of  $\varepsilon$ ;

solution  $\Re z_1(x)$ : same frequency,  
amplitude =  $\mathcal{O}(10^{-5})$

$$\|U\|_{L^\infty(0,1)} \leq C, \quad \|U'\|_{L^\infty(0,1)} \leq \frac{C}{\varepsilon}; \quad \|Z - Z_I\|_\infty \leq C\varepsilon^2, \quad \|Z'\|_\infty \leq C\varepsilon$$

## (2) GOAL: $\varepsilon$ -uniform scheme

$$Z' = \varepsilon \underbrace{\begin{pmatrix} 0 & \beta(x)e^{-\frac{2i}{\varepsilon}\phi(x)} \\ \beta(x)e^{\frac{2i}{\varepsilon}\phi(x)} & 0 \end{pmatrix}}_{=:N(x)=\mathcal{O}(1)} Z, \quad x \in (0, 1); Z(0) = Z_I$$

- **strong asymptotic limit**  $Z^{\varepsilon=0}(x) = Z_I$  ... trivial to capture numerically  
 $\Rightarrow$  **asymptotically correct scheme**; i.e. error =  $\mathcal{O}(\varepsilon^p)$  for some  $p \geq 2$
- **$\varepsilon$ -uniform approximation** (truncated Picard iteration):

$$Z(x) = Z_I + \varepsilon \int_0^x N(y_1) dy_1 Z_I + \varepsilon^2 \int_0^x N(y_1) \int_0^{y_1} N(y_2) dy_2 dy_1 Z_I + \mathcal{O}(\varepsilon^3 x^2 \min(\varepsilon, x))$$

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- Remark: lower order WKB-transformations  $\rightarrow$  **non-const. limit**  $Z^{\varepsilon=0}$   
 $\Rightarrow$  only  **$\varepsilon$ -uniform scheme**; i.e. error =  $\mathcal{O}(1)$   
[Lorenz-Jahnke-Lubich, 2005]

### (3) Approximation of oscillatory integrals

**GOAL:**  $\varepsilon$ -uniform approximation of  $J = \int_{x_n}^{x_{n+1}} \underbrace{\beta(y)}_{\text{smooth}} \underbrace{e^{\frac{2i}{\varepsilon}\phi(y)}}_{\text{oscillatory}} dy$

(+ iterated  $\int$ 's)

+ to arbitrary  $h$ -order !

- **asymptotic method** [Iserles-Nørsett, 2005]:

$$J = -i\varepsilon \left[ \frac{\beta}{2\phi'} e^{\frac{2i}{\varepsilon}\phi} \right]_{x_n}^{x_{n+1}} + \mathcal{O}(\min(\varepsilon^2, \varepsilon h))$$

integration by parts yields higher  $\varepsilon$ -orders but *no*  $h$ -consistency for ODE

- **Filon method** [Iserles-Nørsett, 2005]:

would need exact moments  $J \approx \int_{x_n}^{x_{n+1}} \underbrace{\pi(y)}_{\text{polynomial}} e^{\frac{2i}{\varepsilon}\phi(y)} dy$

# modified asympt. method [AA-B.Abdallah-Negulescu '10]

$$\begin{aligned} J &= e^{\frac{2i}{\varepsilon}\phi(x_n)} \int_{x_n}^{x_{n+1}} \beta(y) e^{\frac{2i}{\varepsilon}[\phi(y)-\phi(x_n)]} dy \\ &= -i\varepsilon e^{\frac{2i}{\varepsilon}\phi(x_n)} \int_{x_n}^{x_{n+1}} \frac{\beta}{2\phi'} \frac{d}{dy} \left( e^{\frac{2i}{\varepsilon}[\phi(y)-\phi(x_n)]} - 1 \right) dy \\ &= -i\varepsilon e^{\frac{2i}{\varepsilon}\phi(x_n)} \frac{\beta}{2\phi'}(x_{n+1}) \left( e^{\frac{2i}{\varepsilon}[\phi(x_{n+1})-\phi(x_n)]} - 1 \right) + \mathcal{O}(\min(\varepsilon h, h^2)) \end{aligned}$$

- idea: include a **zero of oscillatory factor** by shift  
⇒ **change  $\varepsilon$ -power to  $h$ -power**
- 1<sup>st</sup> order consistent,  $\varepsilon$ -asymptotically correct ODE-method

# Resulting methods

- first  $h$ -order:  $Z_{n+1} = (I + A_n^1) Z_n$

$$A_n^1 := -i\varepsilon^2 \frac{\beta}{2\phi'}(x_{n+1}) \begin{pmatrix} 0 & e^{-\frac{2i}{\varepsilon}\phi(x_n)} - e^{-\frac{2i}{\varepsilon}\phi(x_{n+1})} \\ e^{\frac{2i}{\varepsilon}\phi(x_{n+1})} - e^{\frac{2i}{\varepsilon}\phi(x_n)} & 0 \end{pmatrix}$$

- second  $h$ -order:  $Z_{n+1} = (I + A_n^1 + A_n^2) Z_n$

$$A_n^2 := \dots$$



## (4) Error estimates

### Theorem ([ABN '10])

$$\|Z(x_n) - Z_n\| \leq C\varepsilon^p h^{\alpha-1} \min(\varepsilon, h), \quad 1 \leq n \leq N,$$

$$\|U(x_n) - U_n\| \leq C \frac{h^\gamma}{\varepsilon} + C\varepsilon^p h^{\alpha-1} \min(\varepsilon, h), \quad 1 \leq n \leq N$$

$p = 1$

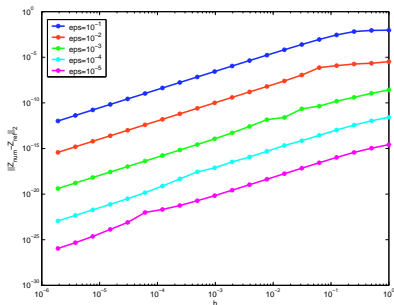
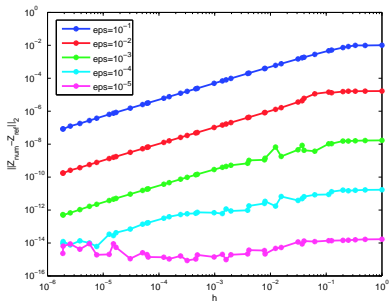
$\alpha = 1, 2 \dots$   $h$ -order of method

$\gamma \dots$  order of quadrature rule for phase  $\phi(x) = \int_0^x \sqrt{a} - \varepsilon^2 \beta \, d\tau$

- Simpson ( $\gamma = 4$ )  $\Rightarrow$  constraint  $h = \mathcal{O}(\sqrt{\varepsilon})$  for 2<sup>nd</sup> order scheme
- $\phi$  exact for potential  $a(x)$  piecewise linear (e.g. in RT-diode)  
 $\Rightarrow \varepsilon$ -asymptotically correct scheme also for  $U$
- simple improvement:  $p = 2$  (note:  $\|Z(x) - Z_I\| \leq C\varepsilon^2$ )

## (5) Numerical example

- $\varepsilon^2 \varphi_{xx} + a(x)\varphi = 0$  with  $a(x) = (x + \frac{1}{2})^2$   
→ phase  $\phi = \int_0^x \sqrt{a(\tau)} - \varepsilon^2 \beta(\tau) d\tau$  explicitly integrable



- $L^2(0, 1)$ -error of  $Z$  (as function of  $h$ ) for first & second order schemes
- schemes are asymptotically correct (error =  $\mathcal{O}(\varepsilon^2)$ , for  $h$  fixed !)

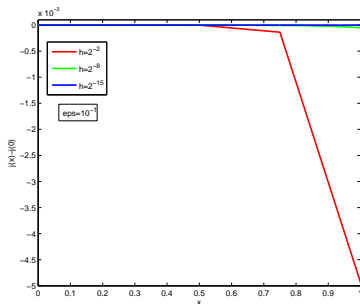
# Current conservation

- continuous current:

$$j(x) := \varepsilon \Im(\overline{\varphi}(x)\varphi'(x)) = \frac{1}{2} Z(x)^\top \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \overline{Z}(x) = \text{const in } x$$

- discrete current:  $j_n := \frac{1}{2} Z_n^\top \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \overline{Z}_n$

- slightly drifts:  $j_{n+1} - j_n =: -\varepsilon^4 \lambda^2 j_n$



- simple fix by scaling possible:  $\tilde{Z}_{n+1} = (1 - \varepsilon^4 \lambda^2)^{-1/2} (I + A_n^1) \tilde{Z}_n$

## (6) Vector valued ODEs

- initial value problem:  $\varphi(x) \in \mathbb{C}^d$

$$\begin{aligned}\varphi''(x) + \frac{1}{\varepsilon^2} A(x) \varphi(x) &= 0, \\ \varphi(0) &= \varphi_0, \\ \varphi'(0) &= \varphi'_0.\end{aligned}$$

- assumptions:  $\mathbb{R}^{d \times d} \ni A(x) = Q(x)a(x)Q^*(x) > 0$ 
  - ▶  $Q(x)$  ... orthogonal, smooth
  - ▶ eigenvalues  $a_j$  remain separated:

$$|a_k(x) - a_l(x)| \geq \delta > 0, \quad a_k(x) \geq \frac{1}{2}\delta, \quad k \neq l$$

- ▶  $\Rightarrow a(x)$  ... diagonal matrix, smooth

## 2 approaches for vector systems

- [L-J-Lubich '05]:  $0^{th}$  order WKB;  
standard treatment of oscillatory integrals  $\rightarrow h < \mathcal{O}(\sqrt{\varepsilon})$
- [Geier-AA '10]:  $1^{st}$  order WKB;  
for oscillatory integrals: shifted asymptotic method or moment-free Filon-type [Olver '06]
- both second  $h$ -order
  
- [Geier '10]: extension to systems with  $1^{st}$  order terms,  
e.g.  $k \cdot p$ -Schrödinger

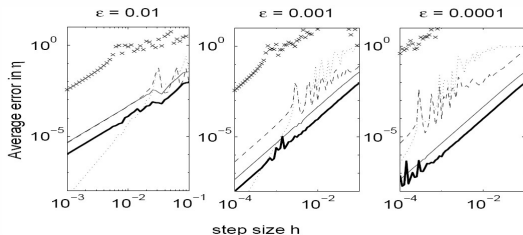
# Numerical example

- example from [L-J-Lubich 2005]:  $d = 2$ ,  $x \in [-1, 1]$

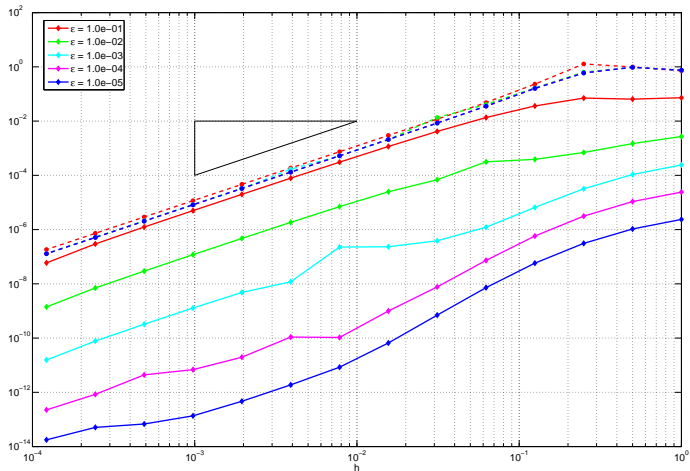
$$a^{\frac{1}{2}}(x) = \left(\frac{3}{2}x + 3\right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \frac{\sqrt{x^2+4}}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$Q(x) = \begin{pmatrix} \cos \xi(x) & -\sin \xi(x) \\ \sin \xi(x) & \cos \xi(x) \end{pmatrix}, \text{ with}$$

$$\xi(x) = \frac{\pi}{4} + \frac{1}{2} \arctan\left(\frac{x}{2}\right), \quad \phi(x) \text{ exactly computable}$$



- [LJL '05]: error  $= \mathcal{O}(h^2)$  (uniformly in  $\varepsilon$ ), but NO  $\varepsilon$ -convergence of  $Z$
- Super-adiabatic transformation* of [Hairer-Lubich-Wanner '06]: similar idea, more complicated formulas, no numerics yet

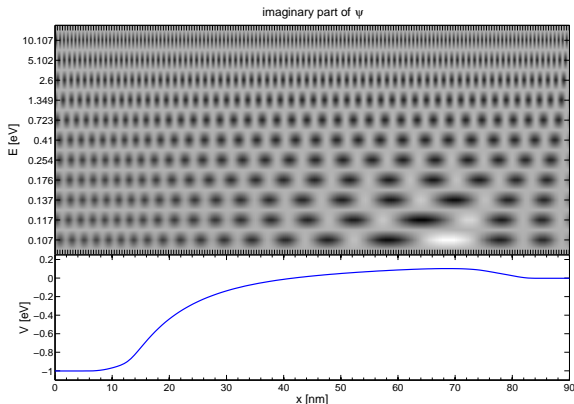


← [LJL'05]

[Geier-AA]

● error in  $Z = \mathcal{O}(\epsilon h \min(\epsilon, h))$

# Scattering in Schrödinger equation



potential  $V(x)$ ;  $\Im\psi(x)$  for several incoming energies  $E$