

Some approximate controllability results for bilinear systems

Sylvain Ervedoza

CNRS & Université Paul Sabatier, Institut de Mathématiques de
Toulouse, équipe MIP

118 route de Narbonne, 31062 Cedex 9 Toulouse, France

`sylvain.ervedoza@math.univ-toulouse.fr`

This talk is complementary to the one of Karine Beauchard. Here, I will present a brief overview on approximate controllability results for bilinear systems. I will mainly focus on three approaches:

- a Lyapunov approach, developed by Nersesyan and Beauchard-Nersesyan;
- an approach based on the control properties of Galerkin approximations of the system, developed by Boscain, Caponigro, Chambrion, Mason, Sigalotti;
- an approach based on the control properties of an easy approximate system deduced by using the scales of the equation, based on the works by S.E., Puel.