Suitability/Entropy/LES

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Jean-Luc Guermond Suitability/Entropy/LES



2 GALERKIN APPROX IN TORUS



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- 2 GALERKIN APPROX IN TORUS
- **3** GALERKIN APPROX + DIRICHLET





- 2 GALERKIN APPROX IN TORUS
- **3** GALERKIN APPROX + DIRICHLET
- ARE SUITABLE SOLUTIONS USEFUL?





- 2 GALERKIN APPROX IN TORUS
- **3** GALERKIN APPROX + DIRICHLET
- ARE SUITABLE SOLUTIONS USEFUL?
- 5 NEW STABILIZATION/NUMERICAL TESTS



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

OUTLINE



Claude Louis Marie Henri Navier



George Gabriel Stokes

BASIC FACTS ABOUT THE NSE
 GALERKIN APPROX IN TORUS
 GALERKIN APPROX + DIRICHLET
 ARE SUITABLE SOLUTIONS USEFUL?
 NEW STABILIZATION/NUMERICAL TESTS

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THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

THE NAVIER-STOKES EQUATIONS

• *u*: velocity, *p*: pressure



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THE NAVIER-STOKES EQUATIONS

- *u*: velocity, *p*: pressure
- Ω is a bounded fluid domain in \mathbb{R}^3

$$\begin{cases} \partial_t u + u \cdot \nabla u + \nabla p - \nu \nabla^2 u = f & \text{in } \Omega \\ \nabla \cdot u = 0 & \text{in } \Omega, \\ u|_{\Gamma} = 0 & \text{or } u \text{ is periodic,} \\ u|_{t=0} = u_0, \end{cases}$$



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- *u*₀ is the initial data.
- f a source term.
- ρ is chosen equal to unity.
- ν is viscosity (inverse of Reynolds number).



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EXISTENCE

 J. Leray (1934): introduces the notion of turbulent solution. A turbulent solution is a weak solution in u ∈ L²(0, T; H¹(Ω)) ∩ L[∞](0, T; L²(Ω)) + global energy inequality.



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$$\partial_t u_{\epsilon} + (\psi_{\epsilon} * u_{\epsilon}) \cdot \nabla u_{\epsilon} + \nabla p_{\epsilon} - \nu \nabla^2 u_{\epsilon} = f$$



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• E. Hopf (1951) *et al.* uses the Galerkin technique to prove existence.





THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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• Are weak solutions unique in the large?





THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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- Are weak solutions unique in the large?
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 \Rightarrow Clay Institute 1M\$ prize.



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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SUITABLE WEAK SOLUTION

Definition (V. Scheffer (1976))

A NS weak solution is said to be suitable weak solutions iff (u, p) is a weak solution and

$$\partial_t(\frac{1}{2}u^2) + \nabla \cdot (u(\frac{1}{2}u^2 + p)) - \nu \nabla^2(\frac{1}{2}u^2) + \nu (\nabla u)^2 - f \cdot u \leq 0.$$

in $\mathcal{D}'((0, T) \times \Omega)$



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SUITABLE WEAK SOLUTION



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SUITABLE WEAK SOLUTION



• $\mathcal{P}^1(S) = \lim_{\delta \to 0^+} \inf\{\sum r_i^1, S \subset \bigcup Q(M_i, r_i), r_i < \delta\}$



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SUITABLE WEAK SOLUTION

Theorem (Caffarelli-Kohn-Nirenberg (1982))

If (u, p) is a suitable weak solutions, then $\mathcal{P}^1(S) = 0$



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SUITABLE WEAK SOLUTION

Theorem (Caffarelli-Kohn-Nirenberg (1982))

If (u, p) is a suitable weak solutions, then $\mathcal{P}^1(S) = 0$

⇒ Singularities (if any) of suitable weak solutions are pointwise in space/time.



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If (u, p) is a suitable weak solutions, then $\mathcal{P}^1(S) = 0$

⇒ Singularities (if any) of suitable weak solutions are pointwise in space/time.

Best partial regularity theorem to date.



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

EX 1: CONSTRUCTION BY MOLLIFICATION

• Leray's mollification

$$\partial_t u_{\epsilon} + (\psi_{\epsilon} * u_{\epsilon}) \cdot \nabla u_{\epsilon} + \nabla p_{\epsilon} - \nu \nabla^2 u_{\epsilon} = f$$



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• CKN's retarded mollification (same idea as Leray's)



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• CKN's retarded mollification (same idea as Leray's)

Theorem (Leray (1934), Duchon-Robert (2000)) Unique weak solution for all t > 0 if $\alpha > \frac{d+2}{4}$, and $u_{\epsilon} \xrightarrow{\rightarrow} u$ (up to subsequences) and u is suitable.

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EX 2: CONSTRUCTION BY MOLLIFICATION/NLGM

• Assume hereafter Ω is the 3D torus



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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• Set
$$N_{\varepsilon} = \frac{1}{\varepsilon}$$



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- Set $N_{\varepsilon} = \frac{1}{\varepsilon}$
- Set $\mathbf{X}_{\varepsilon} = \dot{\mathbb{P}}_{N_{\varepsilon}}$ (velocity space).
- Let $P_{\varepsilon} : \dot{\mathbf{L}}^2(\Omega) \longrightarrow \mathbf{X}_{\varepsilon}$ be L^2 -projection.

$$\dot{\mathsf{L}}^2(\Omega) = \mathsf{X}_arepsilon \oplus (\mathsf{X}_arepsilon)^\perp$$



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

EX 2: CONSTRUCTION BY MOLLIFICATION/NLGM

• Solve for u_{ϵ} , p_{ϵ} s.t.

$$\begin{cases} \partial_t (P_{\varepsilon} u_{\epsilon}) + P_{\varepsilon} u_{\epsilon} \cdot \nabla u_{\epsilon} + \nabla p_{\epsilon} - \nu \nabla^2 u_{\epsilon} = \mathbf{f} \quad \text{in } \Omega \\ \nabla \cdot u_{\epsilon} = 0 \quad \text{in } \Omega, \\ u_{\epsilon} \text{ is periodic}, \quad u_{\epsilon}|_{t=0} = u_0, \end{cases}$$



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Theorem

For all $\epsilon > 0$, problem is well-posed (existence + uniqueness). $u_{\epsilon} \rightarrow u$, $p_{\epsilon} \rightarrow p$ as $\epsilon \rightarrow 0$ (in appropriate spaces, up to subsequences), u and p are suitable weak solution to N.S.

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EX 3: CONSTRUCTION BY HYPERVISCOSITY

• Add a vanishing hyperviscosity (Lions (1959). Ω is the *d*-torus, *d* is the space dimension.

$$\begin{cases} \partial_t u_{\epsilon} + u_{\epsilon} \cdot \nabla u_{\epsilon} + \nabla p_{\epsilon} - \nu \nabla^2 u_{\epsilon} + \varepsilon^{2\alpha} (-\nabla^2)^{\alpha} u_{\epsilon} = f, \\ \nabla \cdot u_{\epsilon} = 0 \\ u_{\epsilon} \text{ is periodic}, \\ u_{\epsilon}|_{t=0} = u_0. \end{cases}$$



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Theorem (Lions (1959), Beirão da Veiga (1985))

Unique weak solution for all t > 0 if $\alpha > \frac{d+2}{4}$, and $u_{\epsilon} \xrightarrow[\epsilon \to 0]{} u$ (up to subsequences) and u is suitable.

THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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QUESTIONS Hyperviscosity Leray regularization Suitable weak solutions Hopf/Galerkin **?**??? Weak solutions



THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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Q1: Is the set of suitable solutions a proper subset of weak solutions?


THE NAVIER-STOKES EQUATIONS EXISTENCE/UNIQUENESS SUITABLE WEAK SOLUTION CONSTRUCTION OF SUITABLE SOLUTIONS

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Q1: Is the set of suitable solutions a proper subset of weak solutions?

Q2: Do the Galerkin solutions end up to be suitable after all?



OUTLINE



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

BASIC FACTS ABOUT THE NSE
 GALERKIN APPROX IN TORUS
 GALERKIN APPROX + DIRICHLET
 ARE SUITABLE SOLUTIONS USEFUL?
 NEW STABILIZATION/NUMERICAL TESTS

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oris Grigorievich Galerkin



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

HYPOTHESES/DEFINITIONS

• Ω is the three-dimensional torus.



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

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 $M_h \subset H^1_{\#}(\Omega)$ for pressure.



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

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abla q_h\|_{\mathbf{L}^2}.$$

• Modify the nonlinear term as follows:

$$b_h(u, v, v) = \begin{cases} (u \cdot \nabla u + \frac{1}{2}u \nabla \cdot u, v) & (\text{Temam, 1967}) \\ ((\nabla \times u) \times u + \frac{1}{2} \nabla (\mathcal{K}_h(u^2)), v) \end{cases}$$

where $\mathcal{K}_h : L^2(\Omega) \longrightarrow M_h$, linear L^2 -stable approximation operator.

THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

HYPOTHESES/DEFINITIONS (ctd.)

Definition (Discrete commutator property)

There is an operator $P_h \in \mathcal{L}(H^1_{\#}(\Omega); X_h)$ (resp. $Q_h \in \mathcal{L}(L^2(\Omega); M_h)$) such that for all ϕ in $W^{2,\infty}_{\#}(\Omega)$ (resp. all ϕ in $W^{1,\infty}_{\#}(\Omega)$) and all $v_h \in X_h$ (resp. all $q_h \in M_h$)

$$\begin{split} \|\phi v_h - P_h(\phi v_h)\|_{H^l} &\leq c \ h^{1+m-l} \|v_h\|_{H^m} \|\phi\|_{W^{m+1,\infty}}, \quad 0 \leq l \leq m \leq 1 \\ \|\phi q_h - Q_h(\phi q_h)\|_{L^2} &\leq c \ h \|q_h\|_{L^2} \|\phi\|_{W^{1,\infty}}. \end{split}$$



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THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

HYPOTHESES/DEFINITIONS (ctd.)

• For instance we want:

 $\|\phi v_h - P_h(\phi v_h)\|_{L^2} \le c h \|v_h\|_{L^2} \|\phi\|_{W^{1,\infty}},$



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- For instance we want:
 - $\|\phi v_h P_h(\phi v_h)\|_{L^2} \le c h \|v_h\|_{L^2} \|\phi\|_{W^{1,\infty}}$,
- FE and wavelet-based approximation spaces have the discrete commutator property (local interpolation properties).



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

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HYPOTHESES/DEFINITIONS (ctd.)

• For instance we want:

 $\|\phi v_h - P_h(\phi v_h)\|_{L^2} \le c h \|v_h\|_{L^2} \|\phi\|_{W^{1,\infty}},$

- FE and wavelet-based approximation spaces have the discrete commutator property (local interpolation properties).
- Fourier-based approximation spaces do not have the discrete commutator property (No local interpolation properties).



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

GALERKIN FORMULATION

• Seek
$$u_h \in C^1([0, T]; X_h)$$
 and $p_h \in C^0([0, T]; M_h)$ such that for all $v_h \in X_h$, all $q_h \in M_h$, and all $t \in [0, T]$

$$\begin{cases} (\partial_t u_h, \mathbf{v}) + \mathbf{b}_h(u_h, u_h, \mathbf{v}) - (\mathbf{p}_h, \nabla \cdot \mathbf{v}) + \nu(\nabla u_h, \nabla \mathbf{v}) = \langle f, \mathbf{v} \rangle, \\ (\nabla \cdot u_h, q) = 0, \\ u_h|_{t=0} = \mathcal{I}_h u_0, \end{cases}$$

where $\mathcal{I}_h : L^2(\Omega) \longrightarrow V_h$, L^2 -stable interpolation operator.



THE MAIN RESULT

THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

Theorem (Guermond (2006))

Under the above hypotheses, if X_h and M_h have the discrete commutator property, the couple (u_h, p_h) convergences to a suitable solution to NS.



THE MAIN RESULT

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Under the above hypotheses, if X_h and M_h have the discrete commutator property, the couple (u_h, p_h) convergences to a suitable solution to NS.

THE HYPOTHESES

THE MAIN RESULT

• Question was open since Scheffer (1977).



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

THE MAIN RESULT (ctd.)

 The main trick: no boundary condition ⇒ easy estimate on the pressure

 $\|p_h\|_{L^{4/3}((0,T);L^2(\Omega))} \leq c.$



THE HYPOTHESES THE GALERKIN FORMULATION THE MAIN RESULT

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• The main trick: no boundary condition \Rightarrow easy estimate on the pressure

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• Use the discrete commutator property to pass to the limit on nonlinear terms: $u_h p_h$ and $u_h u_h^2$.



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• Use the discrete commutator property to pass to the limit on nonlinear terms: $u_h p_h$ and $u_h u_h^2$.

Question: Does the result hold for Dirichlet BCs ?



THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT



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Johann Peter Gustav Lejeune Dirichlet



THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

HYPOTHESES/DEFINITIONS

 Finite element spaces, X_h ⊂ H¹_#(Ω) for velocity and M_h ⊂ H¹_#(Ω) for pressure.



THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

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THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

HYPOTHESES/DEFINITIONS (ctd.)

•
$$\mathbf{V}_h := \{ v_h \in \mathbf{X}_h; (\nabla \cdot v_h, q_h) = 0, \forall q_h \in M_h \}$$



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$$\mathbf{V}_h := \{ v_h \in \mathbf{X}_h; (\nabla \cdot v_h, q_h) = 0, \forall q_h \in M_h \}$$

• Discrete Stokes operator $A_h : \mathbf{V}_h \longrightarrow \mathbf{V}_h$

$$(A_h u_h, v_h) = (\nabla u_h, \nabla v_h), \quad \forall v_h \in \mathbf{V}_h.$$



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• Discrete Stokes operator $A_h : \mathbf{V}_h \longrightarrow \mathbf{V}_h$

$$(A_h u_h, v_h) = (\nabla u_h, \nabla v_h), \quad \forall v_h \in \mathbf{V}_h.$$

• Discrete norm
$$\|v_h\|_{\mathbf{V}_h^s} := (A_h^s v_h, v_h)^{\frac{1}{2}}, \quad \forall s \in \mathbb{R}.$$



THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

PRELIMINARY RESULTS

Lemma

 $\exists c_l > 0$ (non-increasing function) $\exists c_u > 0$ (non-decreasing function), independent of h:

$$c_{l}(|s|) \|v_{h}\|_{\widetilde{\mathbf{H}}_{0}^{s}} \leq \|v_{h}\|_{\mathbf{V}_{h}^{s}} \leq c_{u}(|s|) \|v_{h}\|_{\widetilde{\mathbf{H}}_{0}^{s}}, \quad \begin{cases} -\frac{1}{2} < s < \frac{3}{2}, & \text{lower}, \\ -\frac{3}{2} < s < \frac{3}{2}, & \text{upper} \end{cases}$$



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THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

PRELIMINARY RESULTS

Lemma

 $\exists c_l > 0$ (non-increasing function) $\exists c_u > 0$ (non-decreasing function), independent of h:

$$c_{l}(|s|) \|v_{h}\|_{\widetilde{H}_{0}^{s}} \leq \|v_{h}\|_{\mathbf{V}_{h}^{s}} \leq c_{u}(|s|) \|v_{h}\|_{\widetilde{H}_{0}^{s}}, \quad \begin{cases} -\frac{1}{2} < s < \frac{3}{2}, & \text{lower}, \\ -\frac{3}{2} < s < \frac{3}{2}, & \text{upper} \end{cases}$$

and for all $s \in (-\frac{3}{2}, 0]$

 $c_l(|s|) \|\nabla_h^2 v_h\|_{\widetilde{\mathbf{H}}_0^s} \leq \|A_h v_h\|_{\mathbf{V}_h^s} \leq c_u(|s|) \|\nabla_h^2 v_h\|_{\widetilde{\mathbf{H}}_0^s}, \quad \forall v_h \in \mathbf{V}_h.$

THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

GALERKIN FORMULATION

• Seek
$$u_h \in C^1([0, T]; X_h)$$
 and $p_h \in C^0([0, T]; M_h)$ such that for all $v_h \in X_h$, all $q_h \in M_h$, and all $t \in [0, T]$

$$\begin{cases} (\partial_t u_h, \mathbf{v}) + \mathbf{b}_h(u_h, u_h, \mathbf{v}) - (\mathbf{p}_h, \nabla \cdot \mathbf{v}) + \nu(\nabla u_h, \nabla \mathbf{v}) = \langle f, \mathbf{v} \rangle, \\ (\nabla \cdot u_h, q) = 0, \\ u_h|_{t=0} = \mathcal{I}_h u_0, \end{cases}$$

where $\mathcal{I}_h : L^2(\Omega) \longrightarrow V_h$, L^2 -stable interpolation operator.



THE MAIN RESULT

THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

Theorem (Guermond (2007))

Under the above hypotheses, if X_h and M_h have the discrete commutator property, the couple (u_h, p_h) convergences to a suitable solution to NS.



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Galerkin solutions are suitable (provided discrete commutator property)



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Under the above hypotheses, if X_h and M_h have the discrete commutator property, the couple (u_h, p_h) convergences to a suitable solution to NS.

Galerkin solutions are suitable (provided discrete commutator property)

 \Rightarrow Hopf and Leray solutions are suitable

THE HYPOTHESES PRELIMINARY RESULTS THE GALERKIN FORMULATION THE MAIN RESULT

THE MAIN RESULT (ctd.)

Lemma

There is c independent of h so that,

$$\|\partial_t u_h\|_{H^{\tau-1}((0,T);\mathbf{H}^{-\alpha}(\Omega))}+\|u_h\|_{H^{\tau}((0,T);\mathbf{H}^{-\alpha}(\Omega))}\leq c,$$

for all $\alpha \in [\frac{1}{4}, \frac{1}{2})$ and for all $\tau < \overline{\tau} := \frac{2}{5}(1 + \alpha)$.



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• Slight improvement over Sohr and von Wahl (1986)



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• Slight improvement over Sohr and von Wahl (1986)

Lemma

There is c independent of h such that for
$$s \in [\frac{3}{10}, \frac{1}{2}]$$

 $\|p_h\|_{H^{-r}((0,T);H^s(\Omega))} \leq c,$

for all $r > \overline{r} = \frac{1}{4} + \frac{s}{2}$.



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

OUTLINE



Jean Leray



Heinz Hopf



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UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

UNDER-RESOLVED SIMULATIONS

• At high *Re* numbers, CFD is always under-resolved. For practical purposes $Re \approx \infty$.



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- Q: Should we bother about suitability?


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UNDER-RESOLVED SIMULATIONS

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- *h* is never small enough to guaranty suitability of the approximation.
- Q: Should we bother about suitability?
- A: Yes. (What does suitability means after all)?



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

UNDER-RESOLVED SIMULATIONS

• Let *u*, *p* solve the Navier-Stokes equations.



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UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

UNDER-RESOLVED SIMULATIONS

- Let *u*, *p* solve the Navier-Stokes equations.
- Define the residual

$$R(x,t) = \partial_t u - \nu \nabla^2 u + u \cdot \nabla u + \nabla p - f$$



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• *u*, *p* is suitable if the residual is pointwise dissipative

$$R \cdot u \leq 0,$$
 a.e. $x, t.$



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⇒ The singular sub-scales (if any) are dissipative (at very small scales energy is dissipated)



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

A NEW SUBGRID VISCOSITY MODEL?

• In under-resolved computations

$$R_h(x,t) := \partial_t u_h - \nu \nabla^2 u_h + u_h \cdot \nabla u_h + \nabla p_h - f \neq 0!$$



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UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

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● Under-resolved computations ⇔ There are singular subscales



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

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A NEW SUBGRID VISCOSITY MODEL?

• In under-resolved computations

$$R_h(x,t) := \partial_t u_h - \nu \nabla^2 u_h + u_h \cdot \nabla u_h + \nabla p_h - f \neq 0!$$

- Under-resolved computations ⇔ There are singular subscales
- To guaranty that at the grid scale h, energy is well dissipated (suitability) we should have

$$R_h(x,t) \cdot u_h \leq 0, \qquad \forall x,t$$

UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

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A NEW SUBGRID VISCOSITY MODEL?

• Proposal: Use $R_h(x, t) \cdot u_h$ to construct a subgrid viscosity.



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

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A NEW SUBGRID VISCOSITY MODEL?

- Proposal: Use $R_h(x, t) \cdot u_h$ to construct a subgrid viscosity.
- Define entropy residual:

$$D_h(x,t) := \partial_t (\frac{1}{2}u_h^2) + \nabla \cdot ((\frac{1}{2}u_h^2 + p_h)u_h) - R_e^{-1} \nabla^2 (\frac{1}{2}u_h^2) + R_e^{-1} (\nabla u_h)^2 - f \cdot u_h.$$



UNDER-RESOLVED SIMULATIONS A NEW SUBGRID VISCOSITY MODEL?

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• Define viscosity:

$$\min\left(c_{1}\frac{h^{2}}{\|u_{h}\|_{L^{2}}^{2}}|D_{h}(x,t)|,c_{2}|u_{h}|h\right)$$



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• Define viscosity:

$$\min\left(c_{1}\frac{h^{2}}{\|u_{h}\|_{L^{2}}^{2}}|D_{h}(x,t)|,c_{2}|u_{h}|h\right)$$

Note that |D_h(x, t)| → 0 if there is no subgrid scale! (no consistency problem).





Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows



BASIC FACTS ABOUT THE NSE
 GALERKIN APPROX IN TORUS
 GALERKIN APPROX + DIRICHLET
 ARE SUITABLE SOLUTIONS USEFUL?
 NEW STABILIZATION/NUMERICAL TESTS

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport?

• Solve the transport equation $\partial_t u + \beta \cdot \nabla u = 0$





Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Solution method: Galerkin + entropy viscosity.



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

Stabilization? Entropy? Linear transport?

• Numerical test. Data is in $BV \approx W^{1,1}$, $H^{1/2-\epsilon}$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Viscous regularization: L^1 -norm $\mathcal{O}(h^{1/2})$, L^2 -norm $\mathcal{O}(h^{1/4})$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Convergence \mathbb{P}_1 : L^1 -norm $\mathcal{O}(h^{2/3})$, L^2 -norm $\mathcal{O}(h^{1/3})$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Convergence \mathbb{P}_2 : L^1 -norm $\mathcal{O}(h^{3/4})$, L^2 -norm $\mathcal{O}(h^{3/8})$
- Convergence \mathbb{P}_k : L^1 -norm $\mathcal{O}(h^{\frac{k+1}{k+2}})$, L^2 -norm $\mathcal{O}(h^{\frac{k+1}{2(k+2)}})$?



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport?

• Numerical test \mathbb{P}_1 , h = 0.05, T = 1





Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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• Solve
$$\partial_t u + \partial_x f(u) + \partial_y g(u) = 0$$
.



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Solve $\partial_t u + \partial_x f(u) + \partial_y g(u) = 0$.
- Define entropy pair $E(u) = \frac{1}{2}u^2$, $F(u) = \int uf'(u)$, $G(u) = \int ug'(u)$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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- Define entropy viscosity, $\nu_h(u) = \min(c_1 \frac{|D_h(u)|}{||u||_2^2} h^2, c_2\beta(u)h)$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

Buckley Leverett, \mathbb{P}_2 FE

• Solve
$$\partial_t u + \partial_x f(u) + \partial_y g(u) = 0.$$

$$f(u) = \frac{u^2}{u^2 + (1-u)^2}, \qquad g(u) = f(u)(1 - 5(1-u)^2)$$

Non-convex fluxes (composite waves)

$$u(x, y, 0) = egin{cases} 1, & \sqrt{x^2 + y^2} \leq 0.5 \ 0, & ext{else} \end{cases}$$



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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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KPP (WENO + superbee limiter fails), \mathbb{P}_2 FE

• Solve
$$\partial_t u + \partial_x f(u) + \partial_y g(u) = 0$$
.
 $f(u) = \sin(u), \qquad g(u) = \cos(u)$

Non-convex fluxes (composite waves)

$$u(x,y,0) = egin{cases} rac{7}{2}\pi, & \sqrt{x^2+y^2} \leq 1 \ rac{1}{4}\pi, & ext{else} \end{cases}$$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Euler flows

• Solve 1D Euler equations for perfect gas, $(\gamma - 1)e = T = p/\rho$, $\gamma = 1.4$

• Entropy
$$S = rac{
ho}{\gamma-1} \log(p/
ho^{\gamma})$$

- Entropy residual, $D_h(u) := \partial_t S + \partial_x(uS)$
- Define wave speed $\beta := |u| + (\gamma T)^{\frac{1}{2}}$



Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

Euler flows + Fourier

• Solution method: Fourier + BDF4 + entropy viscosity



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Stabilization? Entropy? Linear transport? Nonlinear scalar conservation laws Euler flows

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Figure: Lax shock tube, t = 1.3, 50, 100, 200 points. Shu-Osher shock tube, t = 1.8, 400, 800 points. Right: Woodward-Collela blast wave, t = 0.038, 200, 400, 800, 1600 points.


CONCLUSIONS/OPEN QUESTIONS

● FE, wavelets, ... (local) ≉ Spectral (global).



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- FE, wavelets, ... have enough built-in "numerical" viscosity.



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QUESTION: What happens for spectral expansions ?



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QUESTION: What happens for spectral expansions ?

QUESTION: Does Weak=Suitable?



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CONCLUSIONS/OPEN QUESTIONS

 The notion of suitability can be useful to construct reasonable subgrid models.



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CONCLUSIONS/OPEN QUESTIONS

- The notion of suitability can be useful to construct reasonable subgrid models.
- A new (very simple) stabilization technique has been proposed and tested.



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