

Finite Volumes for systems of partial differential equations

Advanced Topics from Scientific Computing

TU Berlin Winter 2024/25

Notebook 15

 Jürgen Fuhrmann

CairoMakie

```

1 begin
2     using LinearAlgebra, Printf, LaTeXStrings
3     using ExtendableGrids, VoronoiFVM
4     using ExtendableSparse, LinearSolve
5     using GridVisualize
6     using CairoMakie
7     CairoMakie.activate!(type = "png")
8     default_plotter!(CairoMakie)
9 end

```

A system of reaction-diffusion equations

Assume, we are given n coupled PDEs in $\Omega \subset \mathbb{R}^d$:

Denote n -vectors by bold face and d -vectors by arrows. Let $\mathbf{u}(\vec{x}, t) = (u_1(\vec{x}, t) \dots u_n(\vec{x}, t))$ be a n -vector function.

$$\begin{aligned}
 \partial_t s_1(\mathbf{u}) - \nabla \cdot \vec{j}_1(\mathbf{u}, \vec{\nabla} \mathbf{u}) + r_1(\mathbf{u}) &= f_1 \\
 &\vdots \\
 \partial_t s_n(\mathbf{u}) - \nabla \cdot \vec{j}_n(\mathbf{u}, \vec{\nabla} \mathbf{u}) + r_n(\mathbf{u}) &= f_n
 \end{aligned}$$

In vector form, this can be rewritten as:

$$\partial_t \mathbf{s}(\mathbf{u}) - \nabla \cdot \vec{\mathbf{j}}(\mathbf{u}, \vec{\nabla} \mathbf{u}) + \mathbf{r}(\mathbf{u}) = \mathbf{f}$$

- "Storage" $\mathbf{s} : \mathbb{R}^n \rightarrow \mathbb{R}^n$
- "Reaction" $\mathbf{r} : \mathbb{R}^n \rightarrow \mathbb{R}^n$
- "Flux" $\vec{\mathbf{j}} : \mathbb{R}^n \times \mathbb{R}^{nd} \rightarrow \mathbb{R}^{nd}$
- "Source" $\mathbf{f} : \Omega \rightarrow \mathbb{R}^n$
- $\mathbf{s}, \vec{\mathbf{j}}, \mathbf{r}$ can depend on \vec{x}, t as well.

Similar for nonlinear Robin boundary conditions on $\partial\Omega$:

$$\begin{aligned} j_1(\mathbf{u}, \vec{\nabla}\mathbf{u}) \cdot \vec{n} + a_1(\mathbf{u}) &= b_1 \\ &\vdots \\ j_n(\mathbf{u}, \vec{\nabla}\mathbf{u}) \cdot \vec{n} + a_n(\mathbf{u}) &= b_n \end{aligned}$$

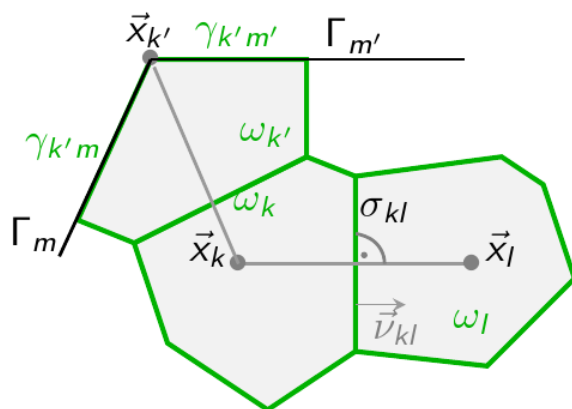
or

$$\vec{\mathbf{j}}(\mathbf{u}, \vec{\nabla}\mathbf{u}) + \mathbf{a}(\mathbf{u}) = \mathbf{b}$$

- "Boundary reaction" $\mathbf{a} : \mathbb{R}^n \rightarrow \mathbb{R}^n$
- "Boundary source" $\mathbf{b} : \partial\Omega \rightarrow \mathbb{R}^n$

The discrete version

The finite volume discretization is based on the two-point flux Voronoi finite volume method.



Let N be the number of control volumes ω_k / collocation points \vec{x}_k . For $k = 1 \dots N$ write

$$|\omega_k| \frac{\mathbf{s}(\mathbf{u}_k) - \mathbf{s}(\mathbf{u}_k^{\text{old}})}{\Delta t} + \sum_{l \in \mathcal{N}_k} \frac{|\sigma_{kl}|}{h_{kl}} \mathbf{g}(\mathbf{u}_k, \mathbf{u}_l) + |\omega_k| \mathbf{r}(\mathbf{u}_k) + |\gamma_k| \mathbf{a}(\mathbf{u}_k) = |\omega_k| \mathbf{f}_k + |\gamma_k| \mathbf{b}_k$$

- ω_k : control volume
- γ_k : boundary interface (\emptyset for interior nodes)
- σ_{kl} : interface between neighboring control volumes
- h_{kl} : distance between neighboring collocation points

With exception of $\vec{\mathbf{j}}$, all constitutive functions introduced above can be used in the discrete version as well. The flux $\vec{\mathbf{j}}$ is replaced by the discrete edge flux $\mathbf{g} : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$.

Dirichlet boundary conditions can be described within this formulation via the penalty method.

Example: a reaction-diffusion problem

Two species u_1 and u_2 move by diffusion in $\Omega = (0, 1)$. Both have initial concentration zero, and starting with $t = 0$, at $x = 0$, u_1 enters the domain with concentration 1. u_1 is not allowed to leave the domain at $x = 1$.

Within Ω , u_1 reacts to u_2 with forward reaction constant k^+ and backward reaction constant k^- . The boundary $x = 0$ is insulating for u_2 , and at $x = 1$, u_2 has forced concentration 0.

$$\begin{aligned} \partial_t u_1 - \nabla \cdot D_1 \vec{\nabla} u_1 + r_1(u_1, u_2) &= 0 \\ \partial_t u_2 - \nabla \cdot D_2 \vec{\nabla} u_2 + r_2(u_1, u_2) &= 0 \\ r_1(u_1, u_2) &= k^+ u_1 - k^- u_2 \\ r_2(u_1, u_2) &= -r_1(u_1, u_2) \\ u_1|_{x=0} &= 1 \\ D_1 \vec{\nabla} u_1 \cdot \vec{n}|_{x=1} &= 0 \\ D_2 \vec{\nabla} u_2 \cdot \vec{n}|_{x=0} &= 0 \\ u_2|_{x=1} &= 0 \\ u_1|_{t=0} &= 0 \\ u_2|_{t=0} &= 0 \end{aligned}$$

```
1 begin
2   const kp = 1
3   const km = 1
4   const D_1 = 0.5
5   const D_2 = 0.1
6 end;
7
```

storage (generic function with 1 method)

```
1 function storage(f, u, node, data)
2   f[1] = u[1]
3   f[2] = u[2]
4   return nothing
5 end
6
```

reaction (generic function with 1 method)

```
1 function reaction(f, u, node, data)
2   r = kp * u[1] - km * u[2]
3   f[1] = r
4   f[2] = -r
5   return nothing
6 end
7
```

bcondition (generic function with 1 method)

```

1 function bcondition(f, u, bnode, data)
2     v = ramp(bnode.time, du = (0, 1), dt = (0, 1.0e-2))
3     boundary_dirichlet!(f, u, bnode, species = 1, region = 1, value = v)
4     boundary_neumann!(f, u, bnode, species = 1, region = 2, value = 0)
5     boundary_dirichlet!(f, u, bnode, species = 2, region = 2, value = 0)
6     boundary_neumann!(f, u, bnode, species = 2, region = 1, value = 0)
7     return nothing
8 end
9

```

flux (generic function with 1 method)

```

1 function flux(f, u, edge, data)
2     f[1] = D_1 * (u[1, 1] - u[1, 2])
3     f[2] = D_2 * (u[2, 1] - u[2, 2])
4     return nothing
5 end
6

```

```

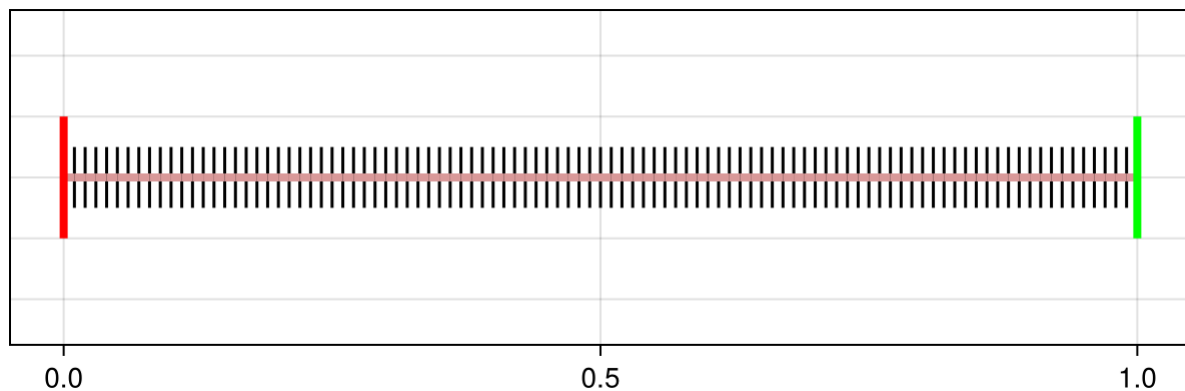
grid = ExtendableGrids.ExtendableGrid{Float64, Int32}
    dim =      1
    nnodes =   101
    ncells =   100
    nbfaces =    2

```

```

1 grid = simplexgrid(0:0.01:1)

```



```

1 gridplot(grid; size = (600, 200))

```

```

system =
VoronoiFVM.System{Float64, Float64, Int32, Int64, Matrix{Int32}}{
    grid = ExtendableGrids.ExtendableGrid{Float64, Int32}(dim=1, nnodes=101, ncells=100,
    nbfaces=2),
    physics = Physics(flux=flux, storage=storage, reaction=reaction, breaction=bconditionic
    ),
    num_species = 2)

```

```

1 system = VoronoiFVM.System(grid; flux, reaction, storage, bcondition, species =
    [1, 2])

```

tend = 10

```

1 tend = 10

```

```

tsol =
t: 291-element Vector{Float64}:
 0.0
 1.0e-5
 2.2e-5
 3.64e-5
 5.3679999999999994e-5
 7.441599999999999e-5
 9.929919999999999e-5
 ⋮
 6.01378830802794
 6.747503004584978
 7.6279606404534235
 8.418640426968949
 9.209320213484474
10.0
u: 291-element Vector{Matrix{Float64}}:
 [0.0 0.0 ... 0.0 0.0; 0.0 0.0 ... 0.0 0.0]
 [0.001 4.554843410322946e-5 ... 1.5480027823016597e-136 1.407262463342749e-137; 9.81447
 [0.0021999999999999997 0.00015908130705043495 ... 1.4009955298788406e-128 1.50105056903
 [0.0036399999999999996 0.0003701927174498243 ... 5.196095466939289e-121 6.5404575523678
 [0.0053679999999999995 0.0007170798487162418 ... 1.0109039306116876e-113 1.489440927662
 [0.0074415999999999999 0.0012480797898037478 ... 1.1121249039591822e-106 1.9100042604902
 [0.0099299199999999998 0.002023311225746713 ... 7.06416191759849e-100 1.407518950270931e
 ⋮
 [1.0 0.9951828455360225 ... 0.6874277376172829 0.6873586244812638; 0.8128968654045824 0.
 [1.0 0.9952259856410248 ... 0.6891158547224582 0.689046719975269; 0.8159125544273736 0.
 [1.0 0.9952552929218204 ... 0.6902622563812656 0.6901931068670524; 0.817962531028575 0.
 [1.0 0.9952708836996275 ... 0.6908719847120693 0.6908028273158894; 0.819053459466289 0.
 [1.0 0.9952801198208002 ... 0.6912331459324508 0.6911639838573514; 0.8196998777537228 0.
 [1.0 0.9952855915529846 ... 0.6914470904421581 0.6913779255916498; 0.8200828856140855 0.

```

```

1 tsol = solve(system, times = (0, tend), Δu_opt = 0.01, Δt_min = 1.0e-5, Δt =
 1.0e-5, log = true)

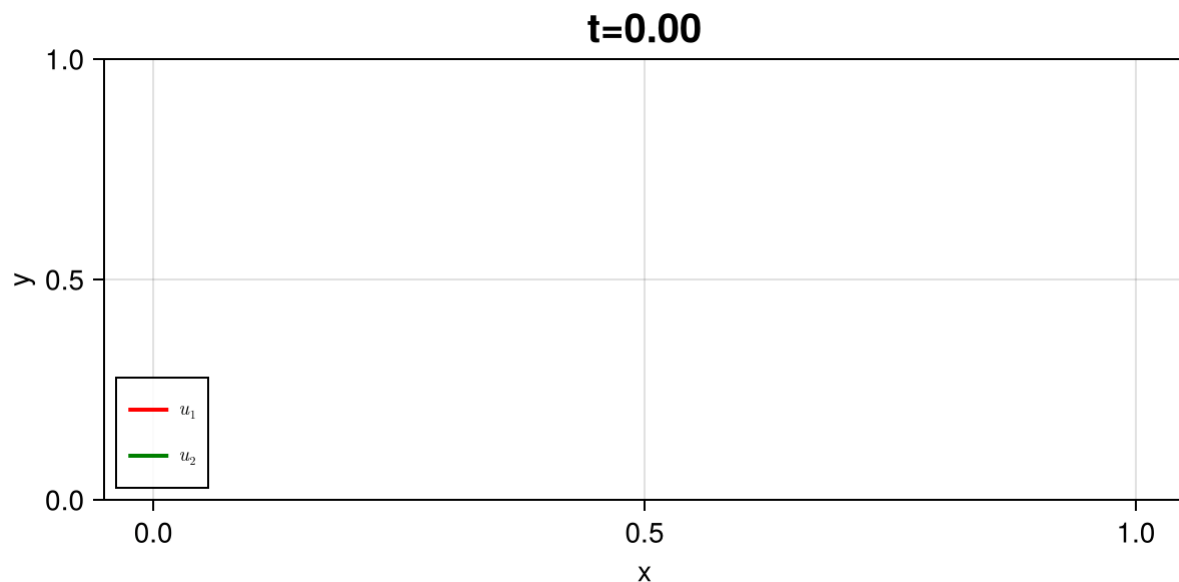
```

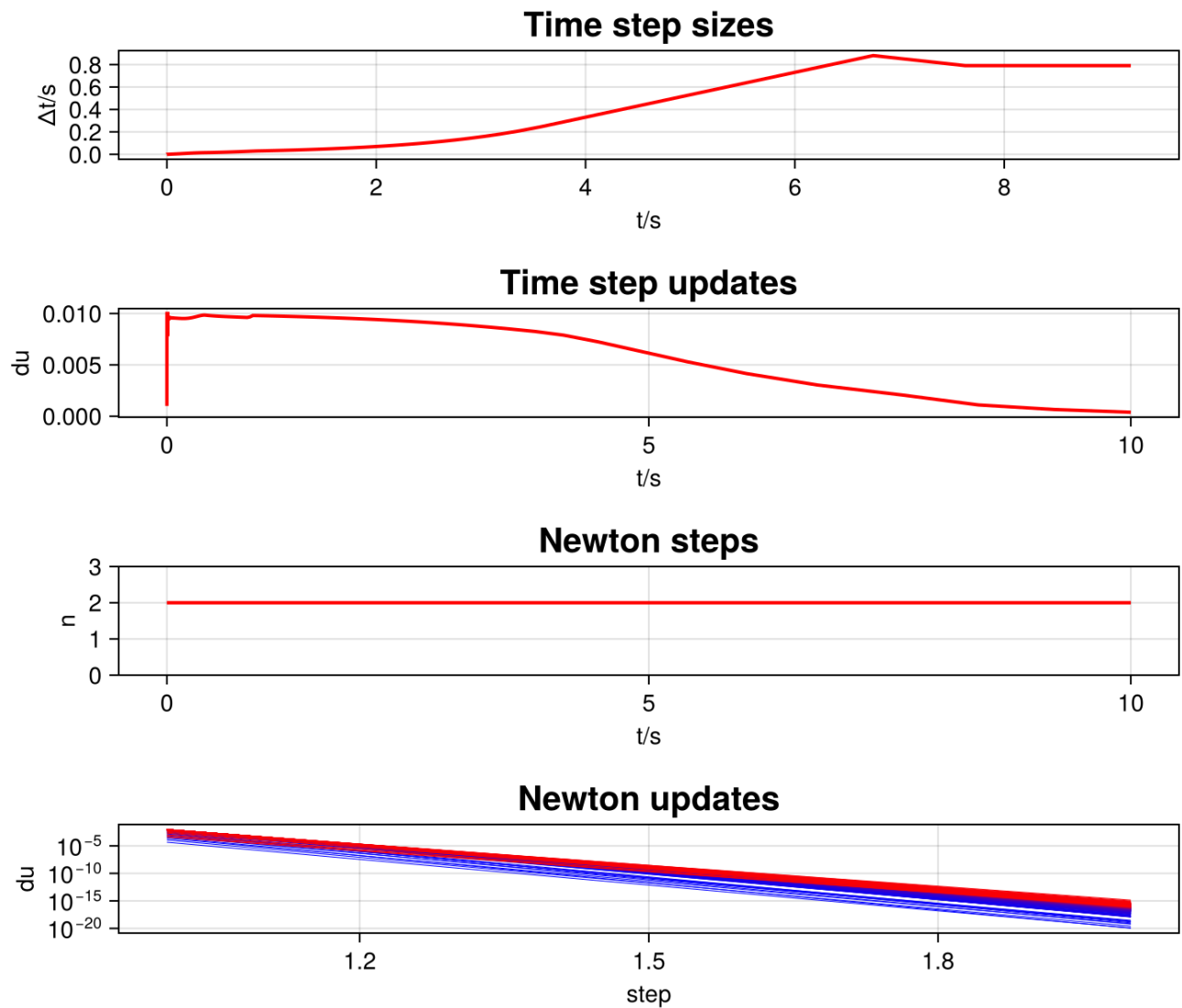
animatesolution1d (generic function with 1 method)

```

1 function animatesolution1d(
2     system, tsol;
3     video = "tmp.gif",
4     nframes = 201,
5     limits = (0, 1),
6     size = (600, 300),
7     pscale_bar = 1.0,
8     Plotter = GridVisualize.default_plotter(),
9     vis = nothing
10 )
11 title = ""
12 vis = GridVisualizer(; size, limits, title, Plotter, legend = :lb)
13 trange = range(extrema(tsol.t)...; length = nframes)
14 movie(vis; file = video) do vis
15     for t in trange
16         title = @sprintf("t=%.2f", t)
17         sol = tsol(t)
18         scalarplot!(vis, system, sol; title, species = 1, label = L"u_1",
19 color = :red)
20         scalarplot!(vis, system, sol; species = 2, label = L"u_2", color =
21 :green, clear = false)
22         reveal(vis)
23     end
24 end
25 return video
26 end

```





```
1 plothistory(tsol)
```

Example: the Brusselator system

Two species interacting via a reaction

$$\begin{aligned}\partial_t u_1 - \nabla \cdot (D_1 \nabla u_1) + (B + 1)u_1 - A - u_1^2 u_2 &= 0 \\ \partial_t u_2 - \nabla \cdot (D_2 \nabla u_2) + u_1^2 u_2 - B u_1 &= 0\end{aligned}$$

with homogeneous Neumann boundary conditons

bruss_storage (generic function with 1 method)

```
1 function bruss_storage(f, u, node, data)
2   f[1] = u[1]
3   f[2] = u[2]
4   return nothing
5 end
6
```

```
ExtendableGrids.ExtendableGrid{Float64, Int32}
  dim =      2
  nnodes =  1681
  ncells =   3200
  nbfaces =   160
```

```
1 begin
2   const A = 2.25
3   const B = 7.0
4   const bruss_D_1 = 0.005
5   const bruss_D_2 = 0.1
6   const pert = 0.1
7   const bruss_tend = 50
8   const dim = 1
9   bruss_X = -1:0.01:1
10  bruss_grid = simplexgrid(bruss_X)
11  bruss_X2 = -1:0.05:1
12  bruss_grid2 = simplexgrid(bruss_X2, bruss_X2)
13 end
14
```

bruss_diffusion (generic function with 1 method)

```
1 function bruss_diffusion(f, u, edge, data)
2   f[1] = bruss_D_1 * (u[1, 1] - u[1, 2])
3   return f[2] = bruss_D_2 * (u[2, 1] - u[2, 2])
4 end
5
```

bruss_reaction (generic function with 1 method)

```
1 function bruss_reaction(f, u, node, data)
2   f[1] = (B + 1.0) * u[1] - A - u[1]^2 * u[2]
3   return f[2] = u[1]^2 * u[2] - B * u[1]
4 end
5
```

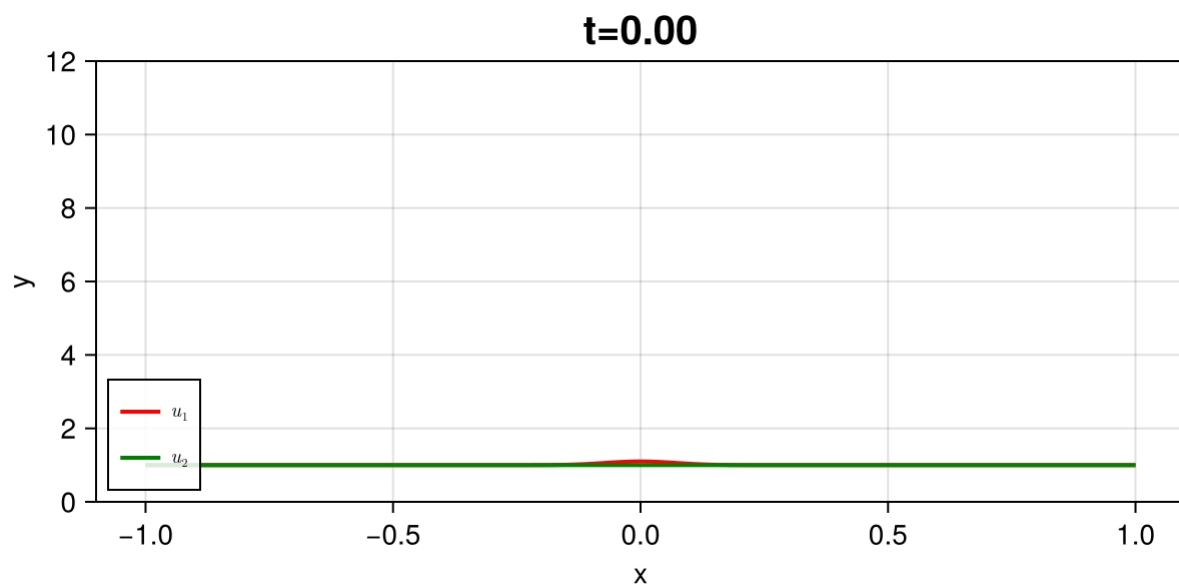
bruss_system =

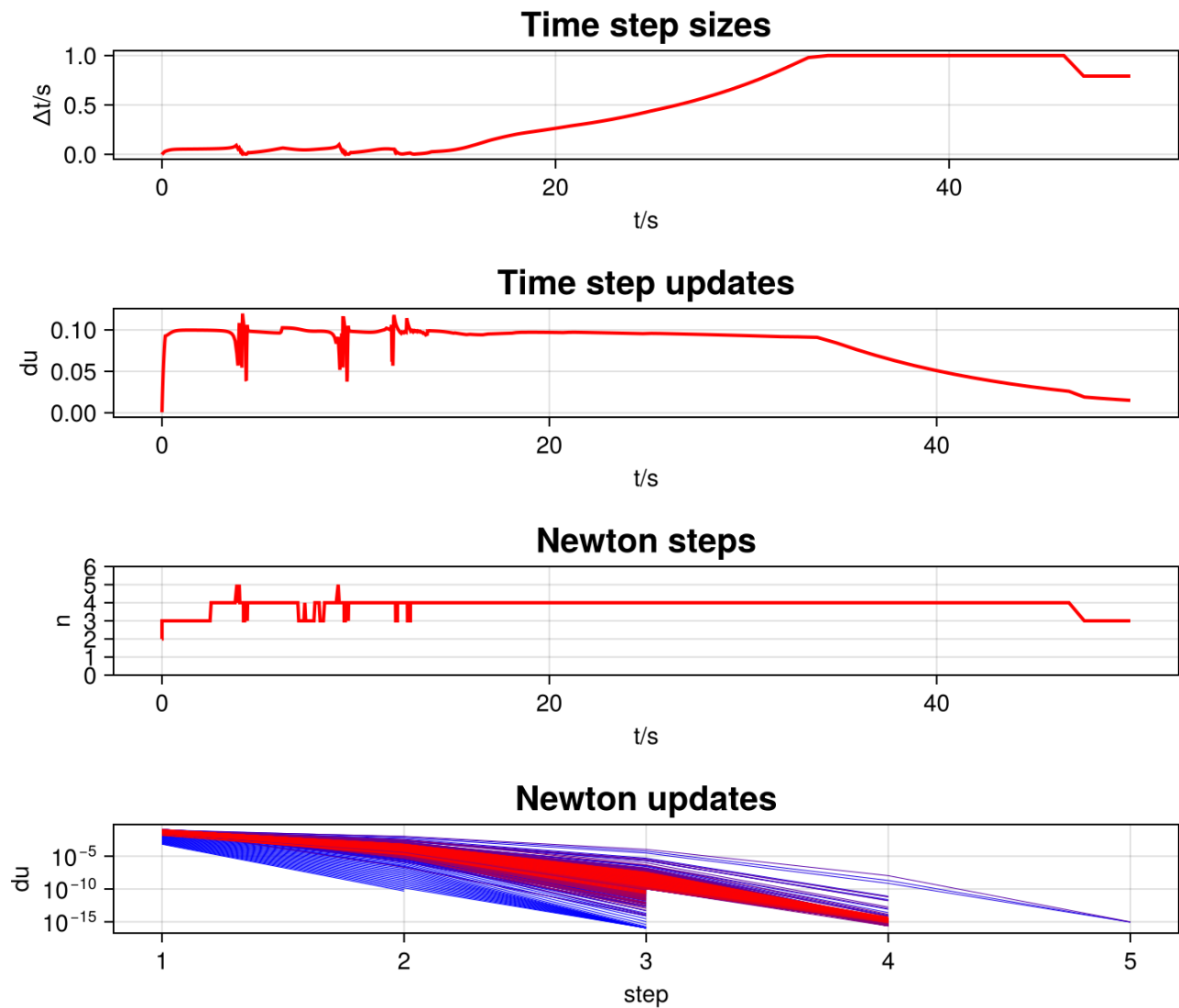
```
VoronoiFVM.System{Float64, Float64, Int32, Int64, Matrix{Int32}}(
  grid = ExtendableGrids.ExtendableGrid{Float64, Int32}(dim=1, nnodes=201, ncells=200,
  nbfaces=2),
  physics = Physics(flux=bruss_diffusion, storage=bruss_storage,
  reaction=bruss_reaction, ),
  num_species = 2)
```

```
1 bruss_system = VoronoiFVM.System(
2   bruss_grid,
3   flux = bruss_diffusion,
4   storage = bruss_storage,
5   reaction = bruss_reaction,
6   species = [1, 2]
7 )
8
```



```
1 begin
2   inival = unknowns(bruss_system)
3   coord = bruss_grid[Coordinates]
4   fpeak(x) = exp(-norm(10 * x)^2)
5   for i in 1:size(inival, 2)
6     inival[1, i] = 1.0 + 0.1 * fpeak(coord[:, i])
7     inival[2, i] = 1.0
8   end
9   bruss_tsol = solve(
10    bruss_system; inival, times = (0, bruss_tend),
11    Δu_opt = 0.1,
12    Δt = 1.0e-4,
13    Δt_min = 1.0e-6, Δt_max = tend / 10, log = true
14  )
15 end;
16
```





```
1 plothistory(bruss_tsol)
```

```
bruss_system2 =
VoronoiFVM.System{Float64, Float64, Int32, Int64, Matrix{Int32}}(
  grid = ExtendableGrids.ExtendableGrid{Float64, Int32}(dim=2, nnodes=1681, ncells=320,
  nbfaces=160),
  physics = Physics(flux=bruss_diffusion, storage=bruss_storage,
  reaction=bruss_reaction, ),
  num_species = 2)
```

```
1 bruss_system2 = VoronoiFVM.System(
2   bruss_grid2,
3   flux = bruss_diffusion,
4   storage = bruss_storage,
5   reaction = bruss_reaction,
6   species = [1, 2]
7 )
```

```

1 begin
2   inival2 = unknowns(bruss_system2)
3   coord2 = bruss_grid2[Coordinates]
4   for i in 1:size(inival2, 2)
5     inival2[1, i] = 1.0 + 0.1 * fpeak(coord2[:, i])
6     inival2[2, i] = 1.0
7   end
8   bruss_tsol2 = solve(
9     bruss_system2; inival2, times = (0, bruss_tend),
10    Δu_opt = 0.1,
11    reltol = 1.0e-10,
12    Δt = 1.0e-4,
13    Δt_min = 1.0e-6, Δt_max = tend / 10, log = true
14  )
15 end;
16

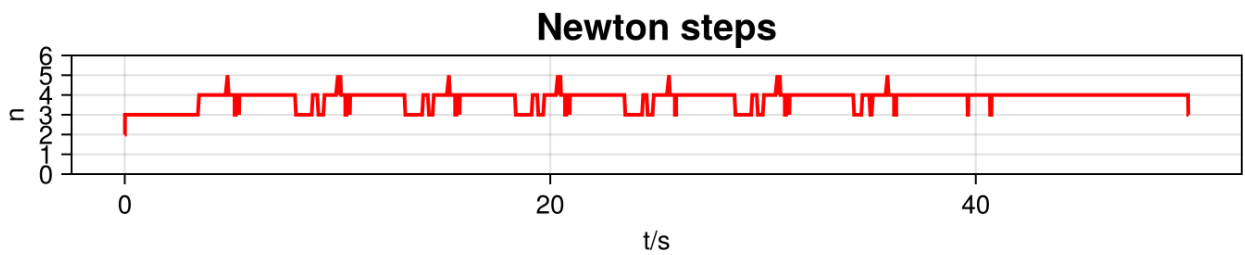
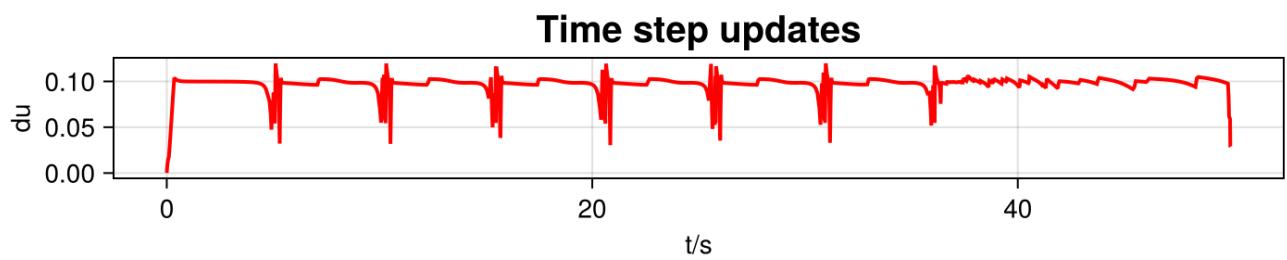
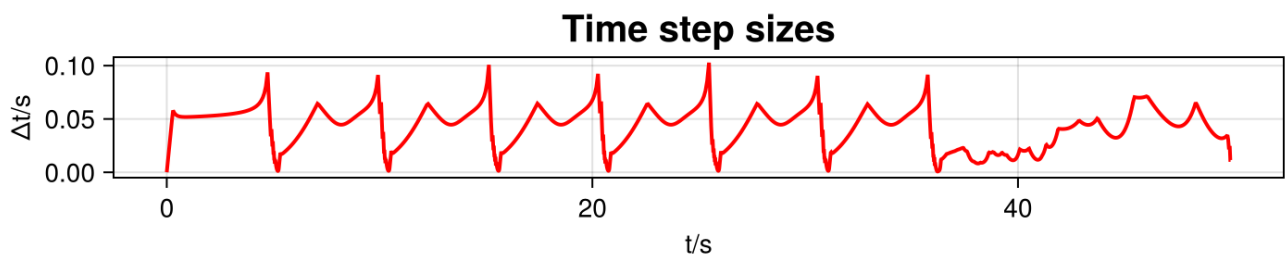
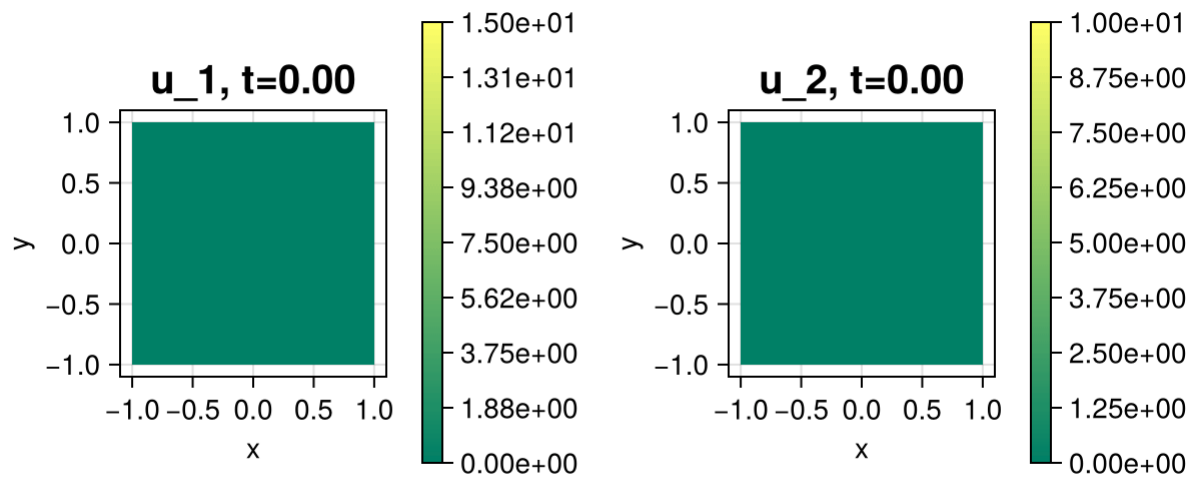
```

animatesolution2d (generic function with 1 method)

```

1 function animatesolution2d(
2   system, tsol;
3   video = "tmp.gif",
4   nframes = 201,
5   size = (600, 300),
6   pscale_bar = 1.0,
7   Plotter = GridVisualize.default_plotter(),
8   vis = nothing
9 )
10 title = ""
11 vis = GridVisualizer(; layout = (1, 2), size, title, Plotter)
12 trange = range(extrema(tsol.t)...; length = nframes)
13 movie(vis; file = video) do vis
14   for t in trange
15     sol = tsol(t)
16     title = @sprintf("u_1, t=%.2f", t)
17     scalarplot!(vis[1, 1], system, sol; title, species = 1, label =
18 "u_1", colormap = :summer, limits = (0, 15))
19     title = @sprintf("u_2, t=%.2f", t)
20     scalarplot!(vis[1, 2], system, sol; title, species = 2, label =
21 "u_2", colormap = :summer, limits = (0, 10))
22     reveal(vis)
23   end
24 end
25 return video
26 end

```



```
1 plothistory(bruss_tsol2, plots = [:timestep sizes, :timestep updates,  
:newton steps])
```

Table of Contents

Finite Volumes for systems of partial differential equations

A system of reaction-diffusion equations

The discrete version

Example: a reaction-diffusion problem

Example: the Brusselator system

